

SIMULATION OF A TANK BATTLE ON COMPUTERS

**A Thesis Submitted
in Partial Fulfilment of the Requirements
for the Degree of
MASTER OF TECHNOLOGY**

**By
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**to the
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CERTIFICATE

This is to certify that the thesis entitled
'SIMULATION OF A TANK BATTLE EXERCISE ON COMPUTERS'
by Capt. Vinay Sagar is a record of work carried out
under my guidance and has not been submitted elsewhere
for a degree.

Sept. 1981

A handwritten signature in black ink, appearing to be 'V. Rajaraman', with a long horizontal stroke extending to the right.

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Capt. Vinay Sagar

ABSTRACT

An interactive simulator for tactical exercise with battle tanks has been described here. The effort has been to make this simulator a logical extension of a sand model exercise, so that a more realistic exercise which is closer to real exercises in field may be achieved.

The topographical details of a map area required to be used, is stored in the memory. The user is permitted to give commands to MOVE and FIRE. The move and fire is simulated taking into consideration the topographical details, characteristics of armour and the firing capability of tanks. The REPORT facility in the simulator helps the user in gaining information regarding tank status and other details used for taking decisions.

It is considered that simulator when fully developed will form a useful aid in exercising a squadron as a team, in which the squadron commander along with his troop commanders can participate.

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CHAPTER 1

INTRODUCTION

In Army, tactical exercises form an important part in troop training. These exercises involve the process of making decisions under visualised situation to resemble true combat situation. Troop commanders are exercised under constraints of carefully planned rules, as they would under combat conditions.

Field Exercises are very costly and have other effects like cost in fuel consumption, wear and tear of equipment and wastage. Wear and tear of tanks is an important factor which reduces the tank life considerably. As such frequent field exercises involving tanks are not possible. Moreover the area available for such exercises is restricted. Built up areas cannot be used for exercise and firing because of the damage it would cause. Also exercise cannot be done in critical areas like borders etc. Therefore at present the use of 'Sand Model' to exercise the personnel in tactics is the most commonly used method. Any form of exercise being at best, a poor substitute for experience, the emphasis is therefore more on realism and greater detail. The objective of this thesis is to develop

a computer based interactive simulation in an effort to replace the sand model exercise with increased reality and more details.

1.1 The Importance of a Simulator;

The simulator comes in between the sand model and field exercise and can have certain advantages over it. Some of the essential features of the simulator are described in the succeeding paragraphs.

The preparation of a sand model is time consuming and even then all the details cannot be represented on it. In contrast in the computer simulation the representation of the topography exists in the memory of the computer which can be more exhaustive than a sand model.

The hypothetical vehicle i.e. tank in this case is 'moved' and can 'fire' taking into account the factors that govern movement such as terrain, gradient, mobility and for fire accuracy of gun, rate of fire and penetration etc.

Visibility and sighting of the tanks is decided by the computer depending on the topographical information available with the computer. Factors that decide visibility like cover, concealment and line of sight is accounted for.

Communication, queries and replies between the simulated tanks by the commanders can be done through the computer.

Freedom of action is available to the participating personnel and pre-determined action is curtailed so that the exercise is allowed to take its course of action.

1.2 Review of Similar work done earlier:

In recent past a lot of thought is going in this direction of simulation on computer mainly because of the economics of time, cost and effort saving that it offers.

Known similar work has been done on 'war gaming' [1], in which a game is described where in two opposing forces are made to 'move' from one point to another according to a battle plan. During this course of movement analysis is done so that if enemy is sighted then it fires a fixed number of rounds/shells on it. In the end the success or failure is evaluated in terms of quantum of forces that have reached their destination.

Another work that has been done has been on 'Computers and Tactical war gaming' [2]. This is a theoretical description on how simulation can be done for a tank battle at squadron level. This work describes how computer can be

used to exercise the commanders i.e. squadron and troop commanders in taking decision in near real life situation. This is more of an interactive process as would be seen in an exercise. The idea for this thesis is based on this work and simulation programmes have been developed in PASCAL for its implementation on Dec 1090.

1.3 Goal of this Thesis:

The goal of this thesis is 'To write the necessary programmes to realise the command and communication repertoire in a higher level computer language for simulation of tank battle'.

To achieve the above goal the following essential features are considered necessary:

- a) A detailed description of battle area topography to be stored in the memory. Roads, rivers, obstacles, minefields, untankable country etc. are depicted so that the exercise can be simulated on any desired type of terrain or area for which map is available.
- b) Detailed description of every participating element, including its characteristics of tank and armament.

- c) The tanks in the memory are 'moved' taking into account the factors that govern movement like terrain, obstacles etc. Gains and losses are decided upon, appropriate to firepower, accuracies of the gun, rate of fire, penetration etc.
- d) Factors deciding visibility such as cover, concealment and direct visibility are catered for.
- e) Tactical decisions are made by the users. They type in command and queries and receive replies in a normal form.
- f) A set of factors additional to that mentioned above like artillery, anti-tank weapons, air support could be included to give more realistic and complex view.

To complete the simulation of a squadron level tank exercise, in addition to this part, development of the requisite interface to couple the necessary consoles and other aids used is required. This could be done as a further development to this thesis. When this is done, then this could be used to exercise the squadrons i.e. the squadron commander along with troop commanders for a tank battle.

1.4 Chapter Summaries:

In the next chapter we review the computer aids available for tactical exercises and war gaming. In this methods available for war gaming, the importance of Tactics/Strategy and any known work in this field will be discussed.

The complete 'over view' of the system will be given in Chapter III. This will give the block diagram of the system developed and what is expected of each block. Interconnections between these blocks and how to use the developed system will be described.

Chapter IV will give some specific algorithms that have been used. Approximations and assumptions made in developing this system will be discussed with possible improvements and the type of computer required for implementation of such a programme.

The graphic aid used by the simulator and a 'test exercise' will be described in the next chapter. The last chapter gives the conclusions and suggestions for further work.

CHAPTER II

WAR GAMING ON COMPUTER

War gaming has become a recognised technique in relatively recent times, but its essence has been a part of the pre-planning that military commanders have done through the ages. The military services would define a war game as a simulation, by whatever means, of a military operation involving two or more opposing forces, conducted, using rules, data and procedures designed to depict an actual or assumed real life situation. The simulated warfare provides a means of gaining experience, identifying errors or short-comings and improving skills without paying the penalties of the real war. Any thing in this world which is as costly as a war impels a search for its substitute.

2.1 War Gaming:

In military most of the important problems are amenable to analytical study. At present war gaming is mainly used for the following purposes:

- a) To train military personnel
- b) To test plans of commanders
- c) For research, to explore new concepts.

Generally the above three purposes are clearly specified and well defined for each game. In some cases it could be used for multiple purpose as well, like for training as well as testing of plans. Games for research are usually conducted to study matters associated with new concepts. They also include the evaluation of plan and/or the formulation of doctrine in the application of new concepts. These three major purposes of war gaming are very much inter-related and also represent the stages of progressive development of war gaming.

War games normally attempt to develop and use models to represent the actions in a game. The model is important in a simulation. In a war game some factors not explicitly quantified in the model can be added by the controller, specified in the rules as input data, or covered as rules in the game assumptions. So effective models of battle can be built for some of the important factors involved in combat, but not all. Too little is known about the geometry of battle. Even information on the rate of casualty production and the resulting effects is inadequate to build precise mathematical equations. Formulae and model from historical records have some validity but have predictive value in a general way only. Although such models are

useful, they do not provide all the interactions and measures of effect needed for many analytical purposes. The object of the game will then be served by comparative rather than absolute casualty figures. Such a model is only as good as the capability of the model builder to build military sophistication and battle logic-expertise into the model.

2.2 Tactics/Strategy:

Some basic characteristics of war games normally found in all of them are:

- a) Every war games simulates a military operation (irrespective of phase or manner of gaming).
- b) Each game involves two or more opposing forces.
- c) Each war game is conducted in accordance with data, rules and procedures acceptable to the military profession.
- d) Every war game represents an actual or assumed real life situation.

An activity cannot be termed a war game unless military forces are involved in movements or operations accompanied by the clash of arms or the threat of such a clash. War

games are played only under conditions of simulated war-fare i.e. shooting, attack, or invasion by one force upon the territory of another. War game rarely consider non-shooting situations unless the situation is an interlude during which forces get into position or range to fight.

Therefore a war game is built upon a situation such as exists or realistically could exist in some locale under certain assumed conditions. The situation is described in detail sufficient for the commander to visualise the conditions under which he must conduct military operation.

Taking the above conditions in view the following ingredients are necessary for war gaming:

- a) Knowledgeable personnel
- b) Special facilities and equipments
- c) Standard data, rules and procedures
- d) A description of the situation to be represented in the game.

2.3 Other work in this Area:

The 'Tin Soldier' which became operable in 1952, is believed to be the first war game designed as a mathematical model for use on a computer in analytical research studies.

This war game is simple and is described as follows. A map is given for the area of interest and on it are

marked the various status of troops of pre-battle conditions for both the opposing forces. It essentially involves two forces, own and enemy forces. Then one man each is permitted to 'head' these forces. Their aim being to guide their forces in an imaginary battle. The battle is then organised to progress under the rules agreed as follows.

- a) Each man is permitted to move his tanks/forces that would correspond to 't' seconds elapsed time on real terrain, consistent with the mobility capabilities of the tank.
- b) After each man moves his tanks/troops according to his military good sense, tanks within range are assumed to bring fire on the opposition. The winner of tank duel is decided by flipping a loaded coin that is supposed to express the odd on the battle outcome in actual fighting between these tanks.
- c) The battle is over as soon as all tanks on either side have been knocked out or have made successful withdrawal from the battle field.

The next step to this was the computerised Monte Carlo version called 'The maximum Complexity Computer Battle', capable of dealing with more of the variables of actual battle. The technique employed is called 'pseudo-random

number generator'. Every time this random number generator is referred, a large sequence of numbers (R) are computed, so that the sequence is practically random as far as the observer is concerned. If the probability of an event 'E' taking place is 'p', p being between '0' to '1', the following procedure simulates the occurrence of E:

if $R < p$, E occurs otherwise not.

Every time procedure is called, R is re-computed and compared with 'p'. Over a large number of calls, 'E' will occur the specified percentage of times. In addition in deciding the occurrence or non-occurrence of probabilistic events, the Monte-Carlo technique also provides for the determination of variables used in simulation in a probabilistic manner.

While the technique described here is satisfactory as a first approximation, it is necessary to add several refinements in practice. The uniform distribution of random variables is not common in practice.

Other methods used for formulation are the 'Next-Event formulation' and 'Fixed time step formulation'. The basic difference between the two is of time of computation. In the first i.e. next event formulation the time period used

is the time that will elapse between two subsequent events. Hence this time period varies as the simulation progresses. Whereas in 'fixed time', the time period of computation is kept constant to a pre-determined value.

With the 'next event' model, the processing of event occurrences proceed occurrence by occurrence as follows. The simulation time is advanced to the time of the earliest future occurrence. That occurrence is processed, then the simulation time is advanced to the time of the (new) earliest occurrence and that occurrence is processed and so on. However, with the fixed time-step model, the processing of event occurrences does not proceed occurrence by occurrence in this way. Rather it proceeds by group or batches of event occurrences. All event occurrences during the time step are processed together.

With the 'next-event' model the need to choose an arbitrary and artificial increment does not exist, and the pit-fall of picking a suitable increment is avoided entirely. In this respect, the next event formulation is preferable to the fixed time step formulations. Further more in a next-event model two event occurrences are not processed as simultaneous events unless they bear identical occurrence times. In a time-step model, on the other hand, batches of

non-simultaneous occurrences are grouped together and made to appear simultaneous. Thus, simultaneity is created where it need not exist. In order to process simultaneous occurrences, any simulation model must make use of some rule for determining the sequence in which to process the occurrences. Fixed time-step simulation then, often takes a group of non-simultaneous event occurrences, forces them to be simultaneous and process them in some sequence.

One situation, however, may require a user to use a time-step model instead of a next-event model. This is the situation where a next-event model takes a prohibitively long time to run on a computer and where the artificialities and inaccuracies of the time step model do not destroy the usefulness of the results. If the time increment, in fixed time step is sufficiently large, it is possible that the fixed time-step simulation may progress significantly faster than the corresponding next event simulation.

In this thesis the model of fixed time-step which can be modified to different values during the simulation is used. The capacity to modify the time step gives the option to the user to make a trade off between accuracy and speed. Thus the user is able to decide during the

simulation process, depending on the status or the situation that exists at that moment. If the user feels that the time step is to be reduced or increased, he can do so at that time.

2.4 Inter-active Simulation:

On computer there are two main types of simulation, one is complete computer simulation and another is man-computer simulation or interactive simulation. In the all computer simulation the input data and the rules are pre-described and given to the computer. The computer then simulates that action and reaches the result or conclusion. In this a number of runs would yield similar results because of the uniform strategy/decision of processing. Whereas inter-active simulation is different and would give different results with each user.

In this, instead of producing a complete history automatically in one continuous operation such a routine processes events until an event is reached where a human decision is necessary or additional input is required. Then the routine causes the computer to wait for appropriate action to be taken before it starts another 'computer phase' of simulation. This is near to real time exercises

conducted by the armed forces and therefore better suited to simulate battle exercises. The simulator described here uses this interactive process of simulation.

Each interval during which the computer waits for input or for decisions is called a 'wait phase' of simulation. During this phase one or more team is in action. A team may be deciding on the movements of units, determining firing and communication policies to be followed, assessing information they have received about their own and enemy's units, and so on. The end of this phase occurs when the information requested by the computer is made available to restart the computer simulation routine.

The most obvious difference between a computer routine for man-computer gaming and a complete computer simulation routine is that the former must be able to 'converse' with the human players. For instance, the routine must be able to inform the players whenever any unit require repair, fuel etc. The routine must also inform the human players of enemy detections, firing of weapons, and damage sustained or inflicted. Each message is delivered through a computer output unit to the appropriate team or player.

An interactive game has some undesirable features which are associated with the alternating of the game. For example,

a 'wait phase' once begun must continue until it produces the decisions or other information which allow another computer phase to be started. Since this corresponds to stopping battles while decisions are being made, it is a poor representation of a real situation. Any attempt to place time limits on the 'wait phase' of the game requires rules which bear little relation to the real situation that one is trying to portray. Also the computer phase of the game must stop whenever any team must furnish information required by the computer simulation routine. This may cause delays unexplainable to one team or the other. For such reasons as these, use of 'synchronized' man-computer game is used where both 'wait' and 'computer' phases run continuously and concurrently with the use of 'clock'.

CHAPTER III

OVER VIEW

Tank battle simulation consists of essentially the storage of data concerning each tank and its subsequent updating depending on the commands given by the user. The data on each tank is stored in a record TNKDAT and has the following fields.

TYPNO: (1..5); Gives the type of Tank. Caters for a maximum of 5 types.

MAPCORD: X,Y; (INTEGER); Gives location of the tank in X and Y co-ordinates.

ORNTASN:(0..360); Gives the direction in which the tank is facing.

AMNCAP :TYP1, TYP2, TYP3: (INTEGER); Gives the amount of ammunition that is available with the tank. Caters for 3 different type of ammunition.

FUELCAP:(INTEGER); Gives the Quantity of fuel that is available with tank.

ALT : (INTEGER); Altitude in metres where the tank is located.

LODIME:(INTEGER); The time taken to load the shells before it is fired once the command to fire has been given.

STATUS:

BOGGED:(BOOLEAN); States whether the tank
is bogged.

MOVING: (BOOLEAN); Whether the tank is moving,
used to calculate rate of fire etc.

CANMOV:(BOOLEAN); Used when command to move
is given.

FIRING:(BOOLEAN); States whether the tank is
firing on target.

CUPOLACLOSED:(BOOLEAN); Used for visibility
calculation.

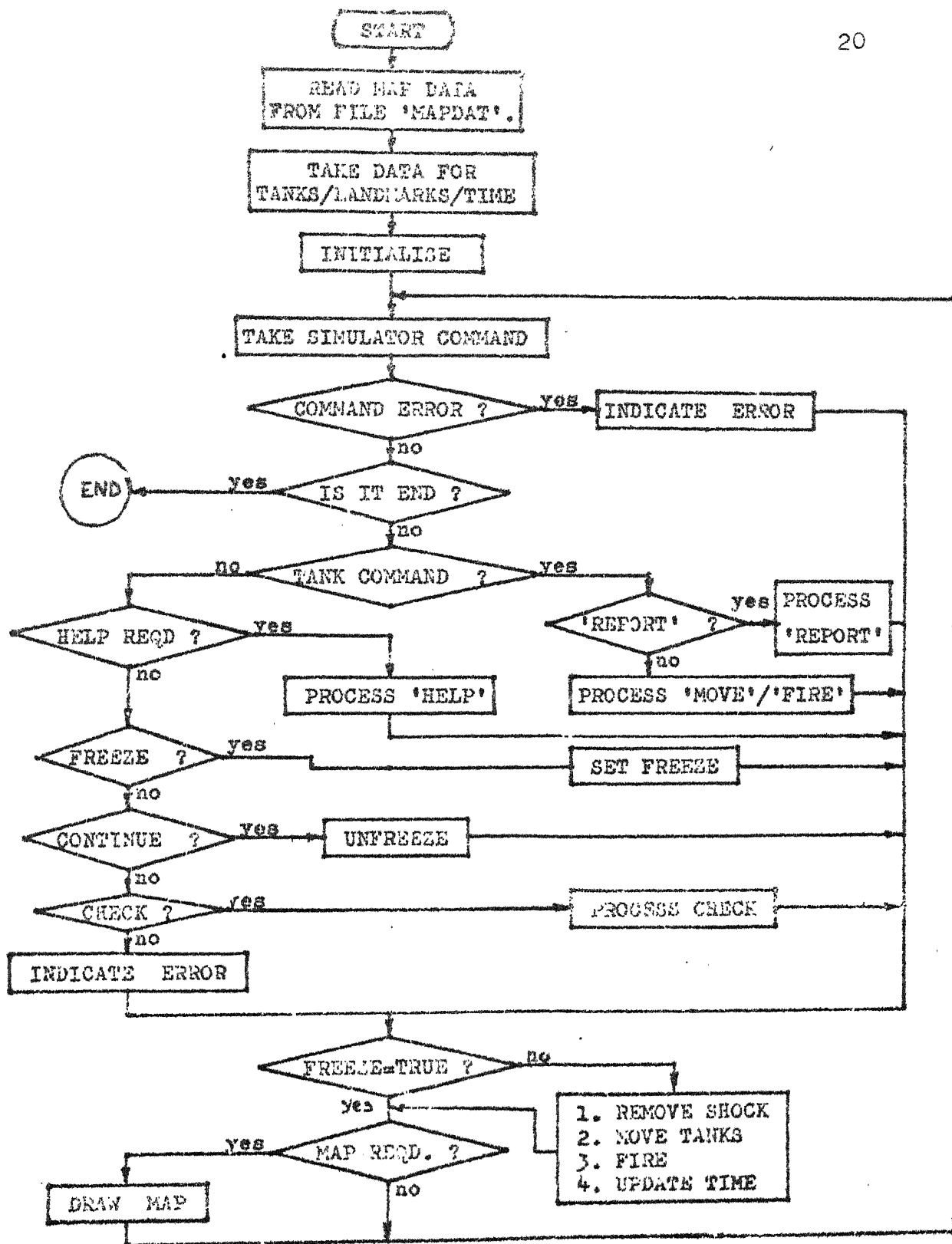
NUETRALISED:(BOOLEAN); Whether tank is incapa-
citated and can take no further part.

SHOCKED:(BOOLEAN); Temporarily out of action,
will not respond in that duration.

Various data from these fields can be 'read' through
REPORT procedures which help the user in taking decision.

These data also form the base for generation of other tables.

The simulation of MOVE and FIRE are done through the
use of temporary tables which are processed to change the
records of the affected tank in TNKDAT.



The flow chart for the simulation process is shown as Fig. 1. This could be divided into the following sub-systems.

- a) Map Generation
- b) Initialization
- c) Command Processing
- d) Report
- e) Information/Help
- f) Update Records
- g) Action
- h) Graphic Display

3.1 Goals for Each Block:

Map Generation:

This part deals with the description of map details. This is a time consuming process and hence is separated from the main programme. The map is drawn with an interactive dialogue. The validity of the input with respect to the restrictions imposed for drawing the map are checked and then a file is created for the use of the main programme. This consists of the following 2 parts.

(a) Checking of Input:

Due to the limitations and economy of computer usage

some restrictions have been imposed for describing the details of a map. They are

- i) Grid points are limited to a maximum of 40x40.
- ii) Each grid point is at a distance of 500 mtr apart.
- iii) Details such as rivers, canals etc. have been approximated as straight lines between turning points.

(b) Creating Data Files:

The above facts are checked as and when the map is being drawn. If it is within these constraints then this data is written into a file 'MAPDAT' which forms an input to the main programme. In addition another file 'MAP' is created to facilitate the drawing of map on Graphic terminal and avoid duplicating of calculation.

Initialise:

This is used for starting the simulation of the exercise. This consists of initialising the following:

(a) Map Details:

Reading the map data from file MAPDAT and storing the map details.

(b) Tank Details:

Initialising/reading the characteristics of the type of tanks used and their location at start.

(c) Graphics:

Initialising the graphic device to be used and resetting its data file MAP for its use.

(d) Land marks:

Taking in interactively the various landmarks that are likely to be used during the exercise and storing them for reference in LMTAB.

(e) Time:

If required, updating the 'Time step' to be used for each iteration. Also takes in the start time of the exercise.

(f) Variables:

Initializing the various pointers arrays and variables used in the programme.

Command Processing:

This is the main block of the system. It takes in one command at a time, analysis it and then appropriately calls the block required. The following facilities are available:

- a) The command is analysed for its syntax error and if error exists, then this is indicated to the user.
- b) Facility to 'freeze' all action and 'un-freeze' it when required.
- c) Updates the time that has elapsed since the start time, if action is not frozen.
- d) Process 'help' for MOVE, FIRE and REPORT.
- e) Change time step if required, during execution of the programme.

Report:

This block is essentially a report back answer to queries addressed to the various tanks. Most of the details are taken from record TNKDAT. The report could be concerning the following.

(a) Location :

This reports the 4 figure grid reference on the map. This could be of

- i) Self
- ii) Another tank.

(b) Status:

This concerns the various activities that a tank could do or is doing. This refers to whether the tank is

- i) Bogged
- ii) Moving
- iii) Can move
- iv) Can shoot
- v) Neutralized

Once a tank is neutralized then it can take no further part in the exercise and will not respond to any command.

(c) Visibility:

Checks if the other tank or location is visible to the addressed tank taking into consideration the following.

- i) Time of day
- ii) Equipment available for visibility at that time of day.
- iii) Cover available to target
- iv) Intermediate obstruction in the line of sight of these 2 points.

(d) Balance:

Balance of 2 commodities can be asked for

- i) Fuel: This includes reserve as well
- ii) Ammunition: This can be asked for a specific type of ammunition i.e.
 - (aa) HE (High Explosive)
 - (ab) AP (Armour Piercing)
 - (ac) SMOKE

By default, if no particular type is specified, then all types will be listed with their balance.

Information/Help:

This contains the information regarding the various modules, facilities that are available and how to use them. It essentially contains information regarding the following:

(a) HELP IN

- i) Commands
- ii) Report
- iii) Move
- iv) Fire

(b) CHECKING

- i) List of land marks defined
- ii) List of Tanks on move
- iii) To change time step
- iv) Set/unset drawing of a map
- v) Display map.

This can be called for by HELP/CHECK and then choose the information in the type required by you. For 'help' it lists out the possible commands in that field with options. This forms the command communication language and is approximated to the actual commands that are normally used, keeping in mind its application on the computer. Commands available are given as Appendix A.

UPDATE RECORDS

When ever any 'Move' or 'Fire' command is given, details regarding the affected tanks is stored in records for further processing in the 'Action' part. This part does the following.

- (a) Checks if the command is correct otherwise the error is indicated to the user.
- (b) If the command is correct then it extracts information to be stored in the respective Move/Fire tables. The details are:
 - i) For Move: This data is stored in a chained record-MOVTAB with following details:
 - (aa) Starting location
 - (ab) Destination
 - (ac) Route - maximum of 10 intermediate points are catered for.

- (ad) Current location
- (ae) Name of tank
- ii) For FIRE: The data for this is stored in record-FIRETAB . It consists of the following details
 - (aa) Name of tank
 - (ab) Target location
 - (ac) Target tank No. if any
 - (ad) No. of shells to be fired.
 - (ae) Rate of fire
 - (af) Hit probability
 - (ag) Type of shells to be fired

These tables form the basis for the other blocks which do the 'Action' part. Once the action is complete then that particular record is deleted from the chain. Therefore only the currently required information is stored in these chains.

Action:

This is essentially simulating the 'move' and 'fire' action in the system. The input to this is taken from the records FIRETAB for 'Fire' and MOVTAB for 'move'. For every cycle of time the following action part is done.

- (a) For MOVE: For each of its record in MOVTAB it does the following:

- i) Checks if the status is not neutralized, if it is not then it will start the move process.
 - ii) It will then take its next objective and calculate the next grid point that it has to move.
 - iii) Before 'moving' to the next grid point, checks for its topography whether there is a river, canal, minefield etc. and takes appropriate action.
 - iv) If it can move to the next grid point then calculates the following
 - (aa) Time taken for this move
 - (ab) Fuel spentand updates both these quantities.
 - v) Thus it will continue till either it reaches its destination, is stopped or the time step is over.
- (b) Fire: When 'fire' is to be done the following is done for each record of its table 'FIRETAB'.

If the status of the tank is not neutralized then each time period, it will fire the shells depending on the following

- i) Rate of fire of the tank depending on whether it is moving or stationary. This is taken from the tank status in TNKDAT.

- ii) Calculate the location of hit taking into consideration the probability of hit and ranging.
- iii) Analysing the hit with respect to the target tank i.e. angle of hit, distance and type of ammunition used. Then accordingly changes the status of the effected tank if needed.
- iv) It will continue this till the required number of shells are fired or time step finishes or is commanded to stop firing.

Graphic Display:

Then lastly the complete activity is displayed on the Graphic terminal. The display consists of the following

- (a) Details of the map which include the following
 - i) Rivers
 - ii) Roads
 - iii) Canals
 - iv) Minefields
 - v) Marshy ground
 - vi) Fields/High grass
- (b) The map displays the area of 20x20 km divided into 40x40 grid points i.e. each grid point is at a distance of 500 mtr apart.

- (c) For referencing on the map, grid marks are available at 2.5 kms distance (5 grid points).
- (d) The 'land marks' defined by the user is also displayed at the location with the assigned name.
- (e) Location of all tanks, as they are located at the time of display of the map.
- (f) Location of hit of the shell at the time of display if there is any.
- (g) Contours are displayed at an interval of 50 mtr. This is done with relative height, with the surrounding ground taken as '0'.

3.2 Interconnections:

The common record for the complete programme is TNKDAT. There are other subsidiary records to this record which are used to update this during the exercise.

The map data generated is primarily used for the 'move' and display purposes. This data is kept in GRIDCHAR. When the move is simulated then details regarding the ground is used for calculation of speed, fuel spent and obstacles enroute.

After calculation of fuel spent and new location, they are updated in the record TNKDAT. If there is any change in status like the tank is bogged, neutralized etc.

the same is changed in the 'status' field of TNKDAT.
Therefore the latest information is stored in the record
TNKDAT.

When 'Fire' has to be done. The shells are fired
from the tank depending on the command given and the same
number as and when fired are reduced from its record of
that particular tank. The location of hit is calculated
and then the effect of shell analysed depending on the type
of shell and location of target damage if any is reflected
through TNKDAT.

'Shocked' is a temporary status wherein the tank
is not able to respond to your command for one cycle of
time. The 'shocked' status removal is directly done through
the main programme.

3.3 How to use the Simulator:

There are 2 programmes in the system which are to be
used in the following sequence.

(a) MAPRIT.PAS

(b) BATTLE.PAS

MAPRIT.PAS

The programme MAPRIT.PAS is used to describe the
topography of the area that is being used. The following

data regarding the details to be described must be available at the time of execution.

(a) RIVERS/CANALS

- i) Direction of flow of water
- ii) Depth of water in cms
- iii) Width in mtrs.

(b) OTHERS: For all others including the rivers and canals the following are required.

- i) Start point
- ii) Turning points

(c) CONTOURS: The height of the contour, in steps of 50 mtr, relative height with the surrounding area taken at '0'.

All the start points and turning points are to be given as 4 figure grid reference. In between these 'Turning Points' the particular detail is approximated as a straight line, hence the points have to be chosen accordingly. While describing the details restriction is also made for the direction in which the next grid point exist. The next grid point has to be in one of the 8 cardinal direction i.e. N/NE/E/SE/S/SW/W/NW.

When the next grid point has been wrongly directed, a message is given i.e. 'going out of map area - direction

wrong'. This point could be recalculated and given.

All contours must be complete i.e. open contours might lead to wrong result hence not allowed.

Any number of such details can be described but each one has to be described separately. For example a river and its tributary will be described separately.

Once this programme is executed two files 'MAPDAT' and 'MAP' are made. They can be used for any subsequent exercise till another map, is defined in a similar manner.

BATTLE.PAS: The execution of this programme will simulate the tank battle. The following data is to be kept ready at the start of the exercise and given when asked.

(a) Type of tank used: Each tank has particular data associated with it for its armour and guns. The following 2 tanks have been catered for:

- i) Vijayanta
- ii) T-55

(b) Location of Troops: Location of 5 troops of a squadron of tanks in 4 figure grid reference.

(c) Time: The time of start of simulation of the exercise is to be given. Along with it the time

step to be used for the exercise is to be given. The minimum time step is calculated as 1 min. This time step can be changed during the execution of the programme as well.

- (d) Land marks: The land marks that are likely to be used during the exercise with their name (less than 12 chars without blanks) and its 4 figure grid reference. Any number of such land marks can be defined.

Once these details have been given the simulation of the exercise starts. There are various commands that can be given. There are basically 2 types of commands i.e. one that is addressed to a tank or otherwise.

The commands that could be addressed to a tank could be

- a) To report about certain attributes
- b) To move from one location to another
- c) To fire at a location or tank.

These are given as Appx. 'A'. The other commands that could be given to the simulator are

- (a) Help: To find the information regarding the commands addressable to the tanks.

(b) Check: The checking/changing of various status during the exercise like

- i) Land marks
- ii) Time step change
- iii) List of tanks on the move
- iv) Setting/Unsetting of map drawing.

(c) Freeze/Cont: This will freeze/unfreeze all the action part. This could be used at the time when some details have to be studied without change in status. 'Cont' will unfreeze the action.

(d) End: Used to terminate the programme.

Generally the following guidelines are to be used during interactive communication with the simulator.

- (a) All sentences or where possibility of a sentence exists, the reply has to end with a '.'.
- (b) A word is taken as 12 characters without blanks.
- (c) The delimiters between words are 'blank'/. /, .
- (d) All single word reply need not end with a '.'.
- (e) For a Yes/No type of dialogue, a simple 'Y' or 'N' could also be used.

The tank addressing is done by 'NO'. The 'NO' consists of 2 parts, Troop number followed by Tank number. Say there

are 5 troops and each troop having 3 tanks then TK 31 will mean Tank No. 1 of troop No. 3.

Normally map drawing will not be available. If this is required, then this will have to be set through CHECK. A one time map drawing is also available through this procedure.

CHAPTER IV

ALGORITHMS

In this chapter some algorithms will be discussed along with the assumptions/approximations that have been made.

4.1 Fire:

The procedure FIRE simulates the 'fire' part. The list of tanks that have been ordered to fire and details required is kept in a linked list of records FIRETAB. In each time step the number of shells that are to be fired is calculated, their effect analysed and reflected in the tank status of the affected tank. Once all the 'ordered' shells have been 'fired' by that tank then that record is deleted from the list.

The various fields in the record FIRETAB are as follows:

SOURCE TK:(INTEGER); Used for storing the number of the tank that is firing.

DEST TK :(INTEGER); Used to stores the number of the tank that is being fired upon. If it is '0' it indicates that firing is on a location.

SOURCE LOC: X,Y:(INTEGER): Stores the location co-ordinates of the tank firing the shells. Used for calculating distance and hit.

DEST LOC: X,Y:(INTEGER); Stores the location of tank being fired upon. Used for hit analysis and 'aiming'.

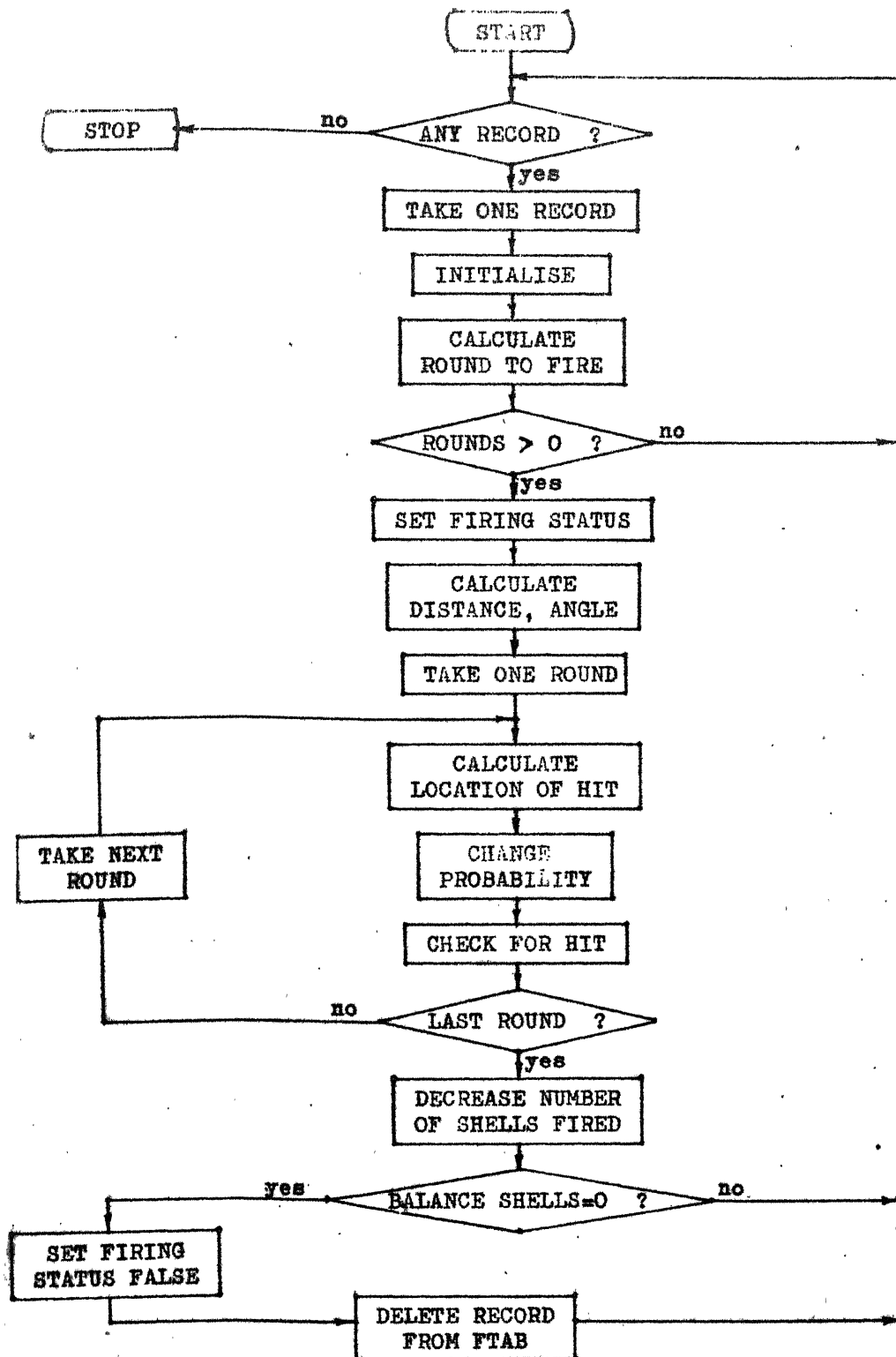
TOTNUM: (INTEGER); Gives the total number of shells that are left to be fired.

TIME: (INTEGER); This gives the load time i.e. time taken by the tank to initially start its first fire.

HIT PROB: (REAL); Gives the hit probability of the shell. Used for calculating the location of hit of the shell.

RATE : (0..15); This gives the number of shells that can be fired in a minute. This depends on the status of tank like moving etc.

ULINK, LLINK:(FPTR); Used to form a linked list of all the tanks that are firing and random deletion on completion of 'fire'.

FIRE

ALGORITHMSFIRE

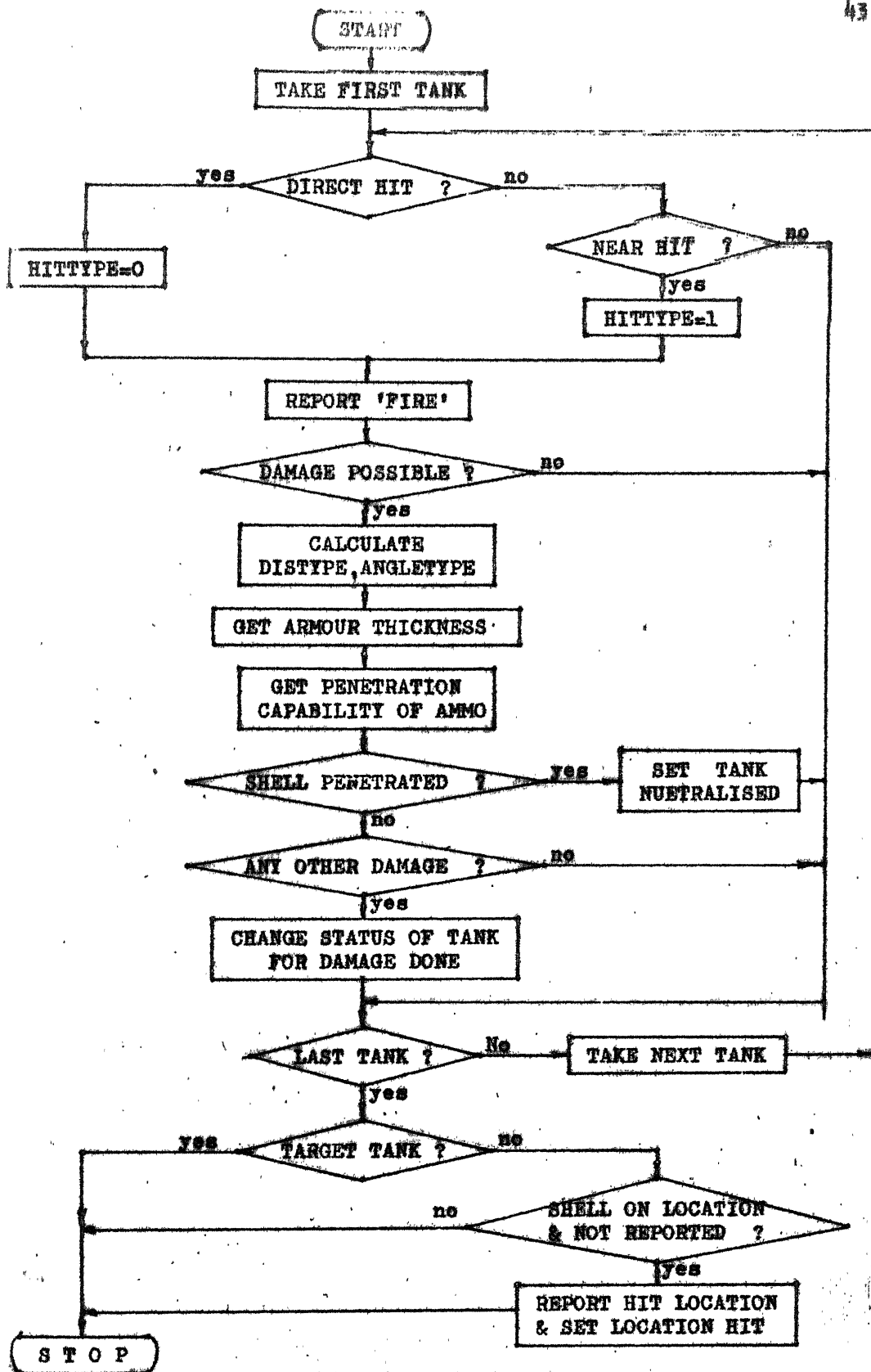
```
1. FOR EACH RECORD IN LIST FTAB DO
    BEGIN
    2. INITIALISE
    3. CALCULATE NUMBER OF ROUNDS TO BE FIRED IN THIS CYCLE
    4. IF NUMBER OF ROUNDS GREATER THAN ZERO THEN
        BEGIN
        5. SET STATUS OF THAT TANK TO FIRING
        6. CALCULATE DISTANCE & ANGLE TO TARGET
        7. FOR EACH ROUND DO
            BEGIN
            8. CALCULATE LOCATION OF HIT
            9. CHANGE PROBABILITY OF HIT
            10. CHECK HIT AND ANALYSE ITS EFFECT
            END
        11. DECREASE NUMBER OF SHELLS FROM BALANCE
        12. IF BALANCE OF SHELLS TO BE FIRED EQUALS ZERO THEN
            BEGIN
            13. SET FIRING STATUS TO FALSE
            14. DELETE THIS RECORD FROM FIRETAB
            END
        END
    END
END
```

END

CHECK HIT: Checks if any of the tanks have been hit directly or indirectly. If it is hit then calls for analysis for damage. Also checks, if the target is a location, then if it has been hit or not.

```
1. FOR EACH TANK DO
    BEGIN
        2. IF HIT LOCATION = TANK LOCATION THEN
            ANALYSE HIT FOR DIRECT HIT
        3. IF HIT LOCATION NEXT TO TANK LOCATION
            THEN ANALYSE HIT FOR INDIRECT HIT
    END
4. IF TARGET IS NOT TANK THEN
    BEGIN
        5. IF HIT LOCATION = TARGET LOCATION AND
            HAS NOT BEEN REPORTED THEN
            BEGIN
                6. REPORT LOCATION HIT
                7. SET THIS TO REPORTED
            END
    END
END
```

ANALYSE HIT: Reports target tank coming under fire and then analyses the hit for any damage it may have done and changes the status if required.



C H E C K H I T

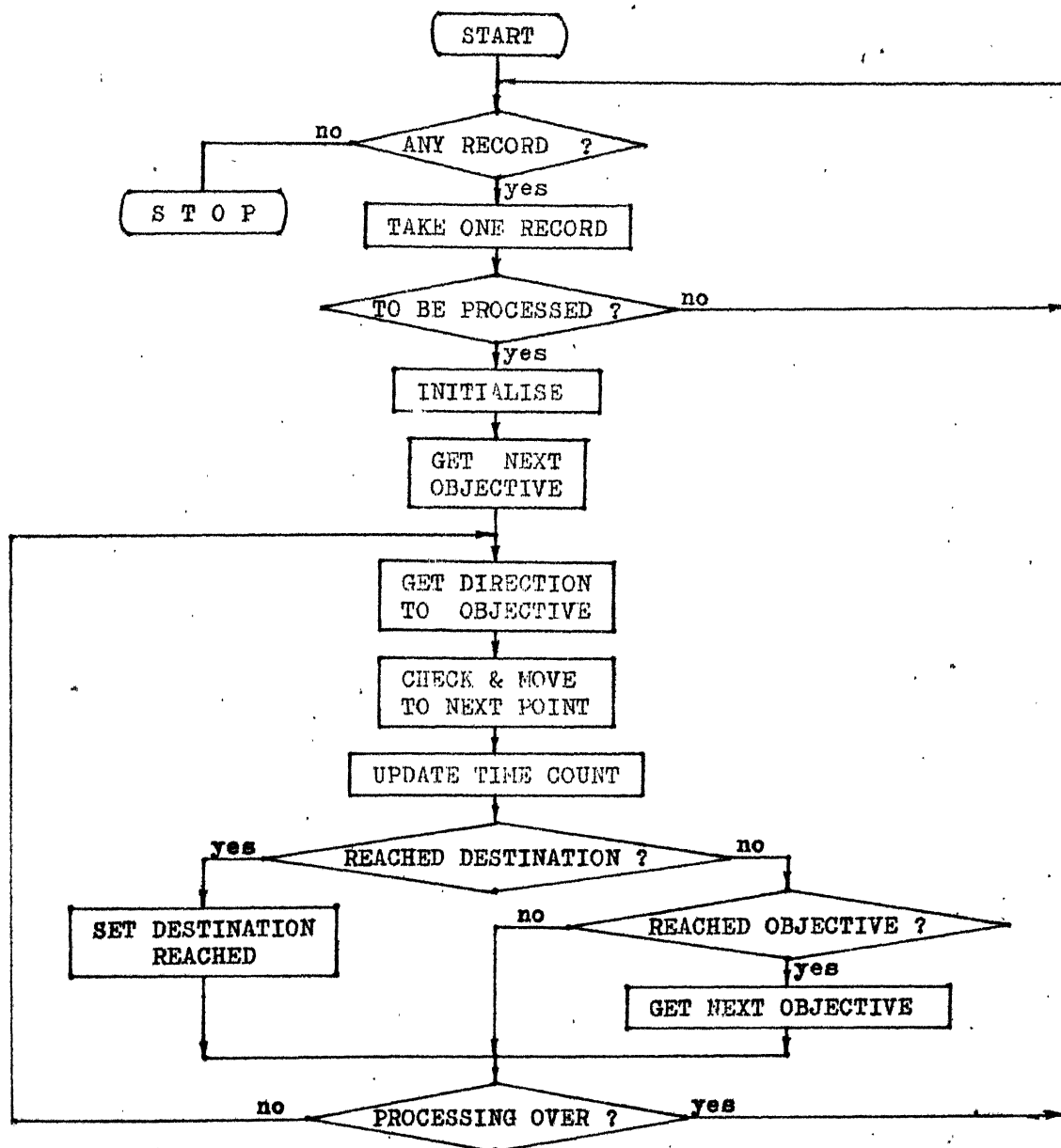
1. IF NOT REPORTED THEN REPORT COMING UNDER FIRE
 2. IF AMMUNITION IS NOT 'SMOKE' OR DISTANCE WITHIN RANGE
BEGIN
 3. CALCULATE DIST-TYPE & ANGLE OF HIT ON THE TANK
 4. GET ARMOUR THICKNESS AT THAT POINT
 5. IF THICKNESS \leq PENETRATING CAPABILITY
THEN SET TANK NUETRALISED
ELSE
 6. ANALYSE FOR EXTENT OF DAMAGE TO TANK AND CHANGE
STATUS ACCORDINGLY
- END

4.2 MOVE TANKS:

This procedure simulates the 'move' part. The details regarding all the tanks that have been ordered to 'move' are kept in a linked list of records in MOVTAB.

In each cycle, each tank in this list is moved for a time period of one time step unless it comes to a halt in between. During the move it 'jumps' from one grid point to another. Before going to the next point it checks for its topography and its possibility to move to that location.

If some obstacle is encountered then it takes action depending on the type of obstacle and command given. The change of status if any is reflected. Once the destination



MOVETANKS

is reached or has been neutralized or incapacitated permanently then this record is deleted from the move list MOV TAB. . The various fields in the record MOV TAB are

TANK NO: (0..99); The number of tank on the move.

SOURCE : X,Y:(INTEGER); The location of the starting point. X and Y coordinates of the tank.

DEST: X,Y: (INTEGER); The location it has to reach ultimately.

LOC: X,Y: (INTEGER); The present location where the tank is located.

ROUTE:ARRAY(1..10) OF CORD:X,Y:(INTEGER); Gives location of the intermediate points.

STATE:(BOOLEAN); Whether the tank is moving or stopped temporarily.

OBJECTIVE:(INTEGER): The total No. of intermediate points.

COURROBJECTIVE:(INTEGER); Present No. of the objective.

ALGORITHMS

MOVE

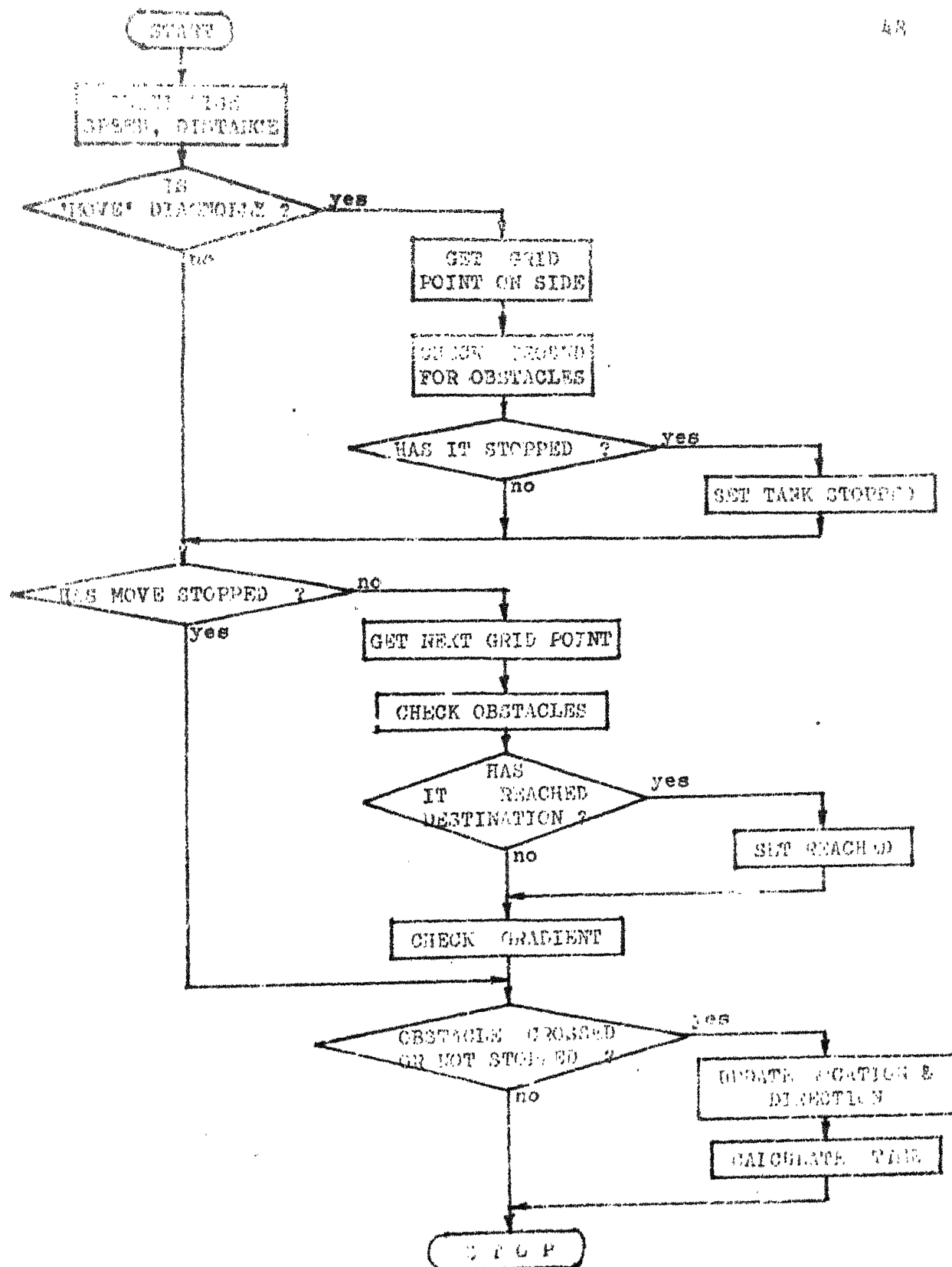
1. FOR EACH RECORD IN LIST DO
BEGIN


```
2. IF RECORD REQUIRES PROCESSING THEN
    BEGIN
    3. INITIALISE
    4. GET NEXT OBJECTIVE
        REPEAT
        5. GET DIRECTION TO OBJECTIVE
        6. COMPUTE TIME FOR MOVE TO NEXT POINT
            IF MOVE IS POSSIBLE
        7. INCREMENT TIME COUNT WITH CURRENT TIME
        8. IF REACHED DESTINATION, SET DESTINATION REACHED
        9. ELSE REACHED OBJECTIVE THEN GET
            NEW OBJECTIVE
        UNTIL REACHED DESTINATION OR FINISHED
            MOVE OR TIME STEP OVER
    END
END
```

COMPUTE TIME

This procedure calculates the next point that the tank is to be moved. Then checks for the type of ground that is there between the 2 points and the next point. If it can move to the next point then the following is calculated.

- a) Speed in this terrain
- b) Distance to the point



COMPUTE TIME

- c) Gradient between the points
- d) Fuel consumed

If it is not possible to move directly then checks if it can encounter this obstacle taking into consideration the following

- a) Type of obstacle
- b) Capability of the tank
- c) If water obstacle, then reports this and asks for orders. If ordered to cross then checks if it can, otherwise gets bogged.

COMPUTE TIME

1. INITIALISE DATA
2. IF TANK TRAVELLING DIAGONALLY THEN CHECK
GROUND IN BETWEEN FOR OBSTACLES
3. IF MOVE NOT FINISHED THEN
BEGIN
4. GET NEXT GRID POINT
5. CHECK GROUND FOR OBSTACLES
6. IF GRADIENT WITHIN LIMIT THEN
BEGIN
7. CALCULATE GRADIENT
8. CALCULATE SPEED CHANGE

9. FUEL CONSUMPTION CALCULATE

END

ELSE

10. STOP TANK AT LOCATION

END

11. IF TANK HAS NOT STOPPED OR HAS CROSSED OBSTACLE

BEGIN

12. MOVE TANK TO NEXT LOCATION

13. UPDATE DIRECTION OF TANK

14. CALCULATE TIME TAKEN TO REACH NEXT POINT

15. CALCULATE FUEL CONSUMED AND

DECREASE FROM BALANCE

END

4.3 Approximation/Assumptions:

For the simulation process some approximations and assumptions are made and these have been done keeping in view the realistic situation and its application on the computer. Some of these have been described in the succeeding paragraphs.

Distance between grid points is kept at 500 meters due to the following reasons:

- (a) Depiction of a large area of 20x20 Kms used for the mobility of the tank.

- (b) Decreasing the number of grid point for the same area thereby decreasing the memory requirements.
- (c) Resolution in graphic display due to limitation of size of display which is fixed.

Straight line approximation between points. In this case error is maximum within 500 mtr length because any number of turning points can be described. The limitation in direction restricted to only 8 is a constraint mainly for storage of data and computation simplicity. The deviation to some extent is acceptable for the exercise purpose.

Only six details like river, canal, road etc. have been included for the map description. Other details which do not have much bearing on the tank battle like anti-personnel mines, barbed wire fence, booby traps etc. have not been considered.

The minimum time step has been kept as 1 minute taking into consideration the maximum time taken by a tank to move from one point to another in the worst possible condition.

The Move and Fire operations are done serially one followed by the other and not parallel as it happens in real time. This is due to computer programme control flow being sequential.

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The 'shocked' tank is kept under shock only for one cycle of time but in actual practice this could be of variable length of time but is approximated as one cycle.

During the firing of shells, the rest of action is frozen as the time of flight is considered very small compared to movement during that period of time.

The height between 2 contours is kept constant throughout this area and height changes only from the next contour onwards.

4.4 Improvements:

In the 'MOVE' commands more general commands like move in formation, and deploy various tactical formation can be adopted and catered for.

Different type of firing tactics can be catered for. Here only 'Ranging' is used by SQUARE ROOT method.

More accurate analysis of hit of the shell could be done. In this, approximation is done upto an accuracy of ± 250 meters which may not be accurate in certain cases.

More details in the map description could be given like tracks, rough or forested area or undulating ground as found in deserts which provide cover to tanks or obstruct visibility could be described and used.

To give more realistic view, Air threat, Artillery and Anti-tank weapons could be incorporated in the simulations.

A combination of MOVE & FIRE tactics used in the case of providing covering fire for an attack could be included.

4.5 Time & Memory Considerations:

The simulator programme is written in Pascal language and implemented on system Dec 1090 computer. All the timings and memory requirement are corresponding to this system.

(a) Programme Storage

BATTLE.PAS	116K bytes
MAPRI.T.PAS	20K bytes

(b) Compilation data using

GPAS (Graphic Pascal)

Memory requirement = 105K bytes

Run time = 11 secs

(c) Programme Execution

- i) Time for initialisation, including
reading of map, tank locations, land marks
Time etc. = 10 secs (average).

- ii) Command Processing Times
 - Simulator command = 33 ms (average)
 - Tank commands = 16 ms (average)
- iii) Action Processing time = 26 ms (average)
- iv) Memory required during execution = 275K bytes (for programme example)

It must be noted that these timings and memory requirements will vary depending on the simulated exercise as dynamic storage and processing is used by the programme.

(d) Type of computer required: For the running of this programme any general purpose computer having the following facilities could be used.

- i) Memory of 64K
- ii) Terminals (TTY) for interactive usage
- iii) Graphic Terminal device (Tectronix display terminal) for the use of displaying of map if required.
- iv) Availability of Pascal graphics with its linking with GPGS.

CHAPTER V



GRAPHIC AIDS

The graphic aid used here for display purpose is Graphic Terminal (Tectronix display terminal) and the language used is Pascal (Graphics).

The size of display on this device is limited to physical size of 15 cms x 15 cms. On this is displayed an area of 20x20 kms divided into 40x40 grid points.

For easy referencing on the map '+' markers are displayed at an interval of 5 grid points i.e. distance of 2.5 kms. each.

The legend for the details represented with the markers that have been used are

- a) RIVER (double line) =
- b) CANAL (nabla) f
- c) ROAD (straight line) -
- d) MINEFIELD (cross) X
- e) MARSHY GROUND (Diamond) 
- f) GRASS/FIELD (Delta) 
- g) CONTOURS (dot) .

The location of hit of a shell is displayed by a * at the location of hit. This is done only for those shells that

are fired in that cycle only. This is done by storing the hit location in a file FIREDT when the Fire procedure is executed. This data is used later by the programme DRAW MAP while drawing the map.

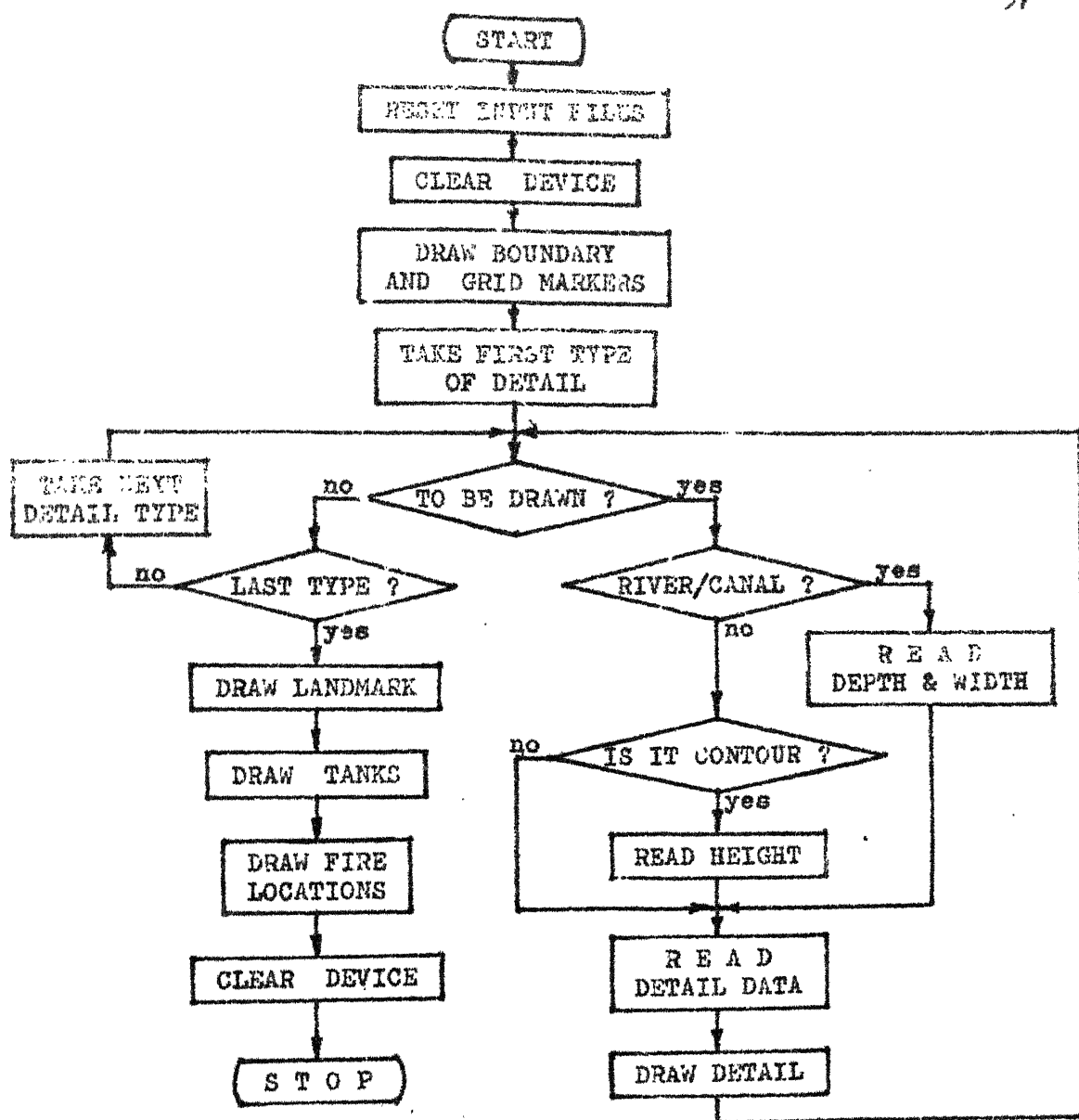
All land marks as described by the user is displayed on the terminal by the name at its location. Its exact location is given by starting character of the land mark name..

All tanks are displayed merely by their numbers i.e. Tank No. 3 of troop No. 1 is displayed as 13 on the displayed. The starting number gives the exact location of the tank.

The programme for Graphic Display is written in Pascal which does not at present provide all the facilities that are otherwise available in Fortran (GPGS). It is also handicapped by the lack of literature on it. Because of these restrictions graphic display is also restricted. This could be developed further as and when the Graphic Pascal becomes more powerful.

5.1 DRAW MAP:

This is the procedure used for drawing the map on the graphic terminal. It takes the input data from files MAPDAT, MAP and FIREDT. Apart from this the data for tanks location



DRAW MAP

is taken from Record TNKDAT and for land marks from LMTAB.
The flow chart for this is shown as Figure 6.

ALGORITHM

1. RESET INPUT FILES MAPDAT, MAP AND FIREDT
2. CLEAR GRAPHIC DEVICE
3. DRAW BOUNDARY AND GRID MARKERS
4. FOR EACH TYPE OF DETAIL DO
 BEGIN
 5. WHILE DETAILS OF THIS TYPE ARE TO BE DRAWN DO
 BEGIN
 6. IF DETAIL IS RIVER OR CANAL READ DEPTH & WIDTH
 7. ELSE IF DETAILS IS CONTOUR READ HEIGHT
 8. READ OTHER DATA REGARDING DETAIL
 9. DRAW DETAIL ON DEVICE
 END
 END
10. DRAW LANDMARKS
11. DRAW TANKS
12. DRAW FIRED SHELL LOCATIONS
13. CLEAR DEVICE IF SEEN

5.2 Test Exercise on Simulator:

For the purpose of demonstration, as to how this simulator could be used, a small test exercise is demonstrated

as follows. Assumptions made for this purpose and a narrative are given below. The aids used for this purpose are, the Hard Copy terminal for recording the interactive communication dialogues between the user and simulator and the 'plotter' to get the map output.

Exercise Background:

There are two states OWN DESH and ENEMY DESH, which have unfriendly relations. The NULLAH river which flows from loc 0127 to loc 3907 is the international boundary between them. Own Desh consists of troops 1,2 and 3 and Enemy Desh has troops 4 and 5. Their locations and various LANDMARKS are shown in MAP-1. Area HUT being a strategically important location Own Desh decides that it must capture it. It ventures to do this in the following manner.

- (a) AIM: Troop 1 and Troop 2 to capture area HUT by 042300 Hrs.
- (b) PLAN: The plan to capture HUT is to be done in 2 phases.
 - i) Phase 1: To cross river NULLAH and make a bridge, Troop 1 in area TREE and Troop 2 in area BRIDGE.

- ii) Phase 2: Troop 2 to move and capture area NODE to give support to Troop 1 for the capture of area HUT.
- (c) PROGRESS OF BATTLE: The course of events that take place during this operation are as follows:
 - i) Because of the increasing tension, Enemy Dosh sends TK 53 to 0723 and TK 42 to 3117 for observation.
 - ii) To divert attention Troop 1 and 2 fire smoke shells at loc 0823 and 3113 to give the impression that a river crossing and attack is being planned in this area.
 - iii) Falling for this TK 51 and TK 41 are sent by Enemy Dosh to locs 0822 and 3113.
 - iv) Troops 1 and 2 cross the river in area CROSS and BRIDGE respectively.
 - v) Troop 3 is brought up to Loc 1717 to give support to these troops.
 - iv) TK 52 moves to 1727 and TK 51 and TK 53 try and cross the NULLAH river to move from the back.

- vii) Troop 2 moves towards NODE and after softening it with fire assaults on it to capture it.
 - viii) Troop 1 after neutralising TK 52 moves to area HUT.
- (d) The activity recorded on the map's correspond to starting of the exercise (MAP-1), after completion of phase 1 (MAP-2) and after completion of the exercise (MAP-3).
- (e) The interactive dialogue used for this exercise is given as Appendix 'B'.

CHAPTER VI

CONCLUSION

A simulator for tactical exercise based on tank has been described here in reasonable detail. This simulator takes into account only a chosen set of factors and follows a specific set of rules built into it. Various constants such as those describing the accuracy of armament, the probability of neutralization and various kinds of hits are used by the simulator.

It is hoped that this simulator will form a logical extension of a sand model exercise, so that it provides more realistic details such that it gets close to real exercises in field. It will enable exercises in critical areas, such as enemy held territory or civilian territory in accessible for real exercises. By co-ordinating intelligence information with known topographical details of critical territories very effective familiarization with such areas can be ensured by simulator exercises.

The simulator goes beyond Armour battle and is very effective in training human decision making element in controlling complex operations, the outcome of which is primarily decided by equipment characteristics, fire power and tactics employed.

Man-machine communication is an important aspect which has been dealt with in this simulation. It is hoped that this will provide to the user how best to use this effectively to deal with a variety of command and control tasks.

It is considered that this simulator could be a useful training aid for Armoured Corp Officers in learning squadron level tactics. The simulator could be used both as a programmed teaching aid for minor tactics as well as training the squadron as a team.

6.1 Further Development:

A small operating system to simulate a squadron level battle to include the following features could be added.

- a) 2 rival squadrons are able to operate independently.
- b) Classification of messages, so that they are routed to various combination of leaders/tanks.
- c) An umpire who gets all messages and commands given by all originators.
- d) Partial display of the areas under their squadron to the Squadron commander and troop commanders.
- e) An element of chance to intercept messages of the opposing forces.

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APPENDIX A

COMMANDS AVAILABLE WITH OPTIONS

COMMAND:: = TK (TANK NUMBER) (REPORT PART)/(FIRE PART)/(MOVE PART).

REPORT PART:: = REPORT LOCATION

STATUS TK (TANK NUMBER)/\$ LOC (GRID REF)/\$

ENEMY

BALANCE AMMUNITION/FUEL HE/SMOKE/AP/ALL/\$

VISIBILITY TK(TANK NUMBER)/LOC (GRID REF)

FIRE PART:: = STOP FIRING

FIRE/SHOOT (NO) HE/AP/SMOKE SHELL(S) AT TK (TANK NUMBER)(DIRECTION)
LN (GRID REF)

MOVE PART:: = MOVE TO (LAND MARK) /\$

ROUTE (LAND MARKS)

(DISTANCE) MTR/METER/KM (DIIRECTION)

OF (LAND MARK)

ROUTE (LAND MARK)

NOTE:

TANK NUMBER :: = TROOP NO. TANK NO.

DIRECTION :: = CLOCK DIRECTION/CARDINAL DIRECTION/DEGREE

CARDINAL DIRECTION:: = NORTH/N, NORTH EAST/NE etc.

LAND MARK :: = DEFINED LAND MARK/GRID REF

LAND MARKS :: = LAND MARK, LAND MARKS/\$

GRID REF :: = FOUR FIGURE GRID REFERENCE

THIS IS A PROGRAMME EXERCISE FOR TANK BATTLE AT SQUADRON LEVEL. YOU ARE REQUIRED TO TYPE IN COMMAND IN THE FORMAT SPECIFIED AND IT WILL BE EXECUTED. THE FOLLOWING POINTS NEED PARTICULAR ATTENTION:-

- 1 THE COMMAND MUST BE TYPED STARTING WITH <TK> OR OTHER COMMAND
- 2 THE COMMAND MUST END WITH <.>
- 3 IN CASE OF HELP TYPE <HELPCCMD> OR <HELP>
- 4 TO TERMINATE THE PROGRAMME TYPE <END.>
- 5 AFTER YOU HAVE WRITTEN YOUR COMMAND GIVE CARRIAGE RETURN
- 6 IF YOU WANT THESE COMMANDS TO TYPED THEN TYPE COMMAND <CHKPTS.

READY TO START NOW

PLEASE GIVE THE TYPE OF TANK USED -

if it is VIJAYANTA then type "v"

if it is T-55 then type "T"

type of tank :V

PLEASE GIVE THE LOCATION OF THE VARIOUS TROOPS OF YOUR SQUADRON

YOU ARE REQUIRED TO GIVE ONLY THE FOUR FIGURE GRID REFERENCE

TROOP NO 1:1519

TROOP NO 2:2511

TROOP NO 3:1511

TROOP NO 4:3133

TROOP NO 5:0531

IMPORTANT:note that the map details have been taken from your file ="MAP"

DO YOU WANT TO DEFINE LANDMARKS ?Y

TYPE IN LANDMARKS IN THE FOLLOWING FORMAT [<LM> <GR>.]

WHEN YOU HAVE FINISHED then type [FINISH.]

INPUT:HILL 1509.

INPUT:RDJN 2505.

INPUT:CROSS 1818.

INPUT:BRIDGE 2513.

INPUT:NULLAH 1021.

INPUT:TREE 1523.

INPUT:HUT 2129.

INPUT:NODE 2929.

INPUT:FIELD 1733.

INPUT:FINISH.

DO YOU WANT THE TABLE OF LANDMARKS ?N

DO YOU WANT TO CHANGE TIMESTEP? [BY DEFAULT IT IS TAKEN AS 1 MIN] :Y

PLEASE TYPE THE TIMESTEP IN FORMAT [<TIME> HR/MIN/SEC .] 13 MIN.
GIVE TIME OF START OF EXERCISE IN (HR,MIN) 4 FIGURES:1900

YOUR COMMAND:TK 42 MOVE TO 3117 ROUTE 3529,3519.

TIME:19: 3: 0

ROGER!

YOUR COMMAND:TK 53 MOVE TO 0723 ROUTE 0425.

TIME:19: 6: 0

ROGER!

TANK 4 2 REPORTING FROM LOCATION 35 24 CANAL OBSTACLE AHEAD
with MAIN CHARACTEREstics AS FOLLOWS:="

DIRECTION SOUTH WEST ==>> NORTH EAST
APPROX WIDTH 50 METERS
APPROX DEPTH 25 CMS
SHOULD I NEGOTIATE THE OBSTACLE or CHANGE COURSE ?
TYPE IN a "C" FOR CHANGING COURSE OR A "GO" TO CONTINUE:GO
TANK 4 2 REPORTING > CANNOT NEGOTIATE THE CANAL - SIDE ARE VERY STEEP

TK 5 3 REPORTING REACHED DESTINATION 723
YOUR COMMAND:TK 13 FIRE 6 SMOKE SHELL LN 0823.

TIME:19: 9: 0

TK 13 REPORTS GIVING EFFECTIVE FIRE ON LN 823
YOUR COMMAND:TK 22 FIRE 6 SMOKE SHELL LN 3113.

TIME:19:12: 0

TANK 22 REPORTS GIVING EFFECTIVE FIRE ON LN 3113
YOUR COMMAND:TK 41 MOVE TO 2713 ROUTE 3527,3525,2725.

TIME:19:15: 0

ROGER!

YOUR COMMAND:TK 51 MOVE TO 0822 ROUTE 0425.

TIME:19:18: 0

ROGER!

TK 5 1 REPORTING REACHED DESTINATION 822	
YOUR COMMAND:FREEZE.	TIME:19:21: 0
YOUR COMMAND:TK 13 MOVE TO 1922 ROUTE CROSS.	TIME:19:21: 0
ROGER!	
YOUR COMMAND:TK 12 MOVE TO 1624 ROUTE TREE.	TIME:19:21: 0
ROGER!	
YOUR COMMAND:TK 23 MOVE TO 2517.	TIME:19:21: 0
ROGER!	
YOUR COMMAND:TK 22 MOVE TO 2717 ROUTE BRIDGE.	TIME:19:21: 0
ROGER!	
YOUR COMMAND:TK 32 MOVE TO 1717 ROUTE 1910,2111.	TIME:19:21: 0
ROGER!	
YOUR COMMAND:TK 33 MOVE TO 1517 ROUTE 0911.	TIME:19:21: 0
ROGER!	
YOUR COMMAND:TK 11 FIRE 8 HE SHELL LN 1123.	TIME:19:21: 0
YOUR COMMAND:TK 21 FIRE 8 HE SHELL LN 2717.	TIME:19:21: 0
YOUR COMMAND:CHECK.	TIME:19:21: 0
THE FOLLOWING CHECKS ARE POSSIBLE	
LISTING LANDMARKS TYPE "L"	
LISTING CURRENTLY MOVING TANKS-"T"	
DRAWINGG THE MAP "M"	
CHANGING TIMESTEP & TIME "C"	
SETTING TO DRAW THE MAP-"S"	
DELETING THE SET MAP DRAWING-"D"	
RETURN-"R"	
CHECK REQOURED FOR:C	
DO YOU WANT TO CHANGE TIME STEP? (BY DEFAULT IT IS TAKEN AS 1 MIN) :N	

GIVE TIME OF START OF EXERCISE IN (HR,MIN) 4 FIGURES:1921
YOUR COMMAND:CONT,

TIME:19:21: 0

TANK 1 2 REPORTING FROM LOCATION 16 19 RIVER OBSTACLE AHEAD
with MAIN CHARACTERISTICS AS FOLLOWS:-

DIRECTION NORTH WEST ==> SOUTH EAST
APPROX WIDTH 100 METERS
APPROX DEPTH 75 CMS
SHOULD I NEGOTIATE THE OBSTACLE or CHANGE COURSE ?
TYPE IN A "C" FOR CHANGING COURSE OR A "GO" TO CONTINUE:GO

TANK 2 3 REPORTING FROM LOCATION 24 13 RIVER OBSTACLE AHEAD
with CHARACTERISTICS AS FOLLOWS:-

DIRECTION NORTH WEST ==> SOUTH EAST
APPROX WIDTH 100 METERS
APPROX DEPTH 75 CMS
SHOULD I NEGOTIATE THE OBSTACLE or CHANGE COURSE ?
TYPE IN A "C" FOR CHANGING COURSE OR A "GO" TO CONTINUE:GO

YOUR COMMAND:TK 52 MOVE TO 1728 ROUTE 0534,1734.

TIME:19:43: 0

ROGER!

TANK 11 REPORTS GIVING EFFECTIVE FIRE ON LN 1123
TANK 21 REPORTS GIVING EFFECTIVE FIRE ON LN 2717
YOUR COMMAND:TK 53 MOVE TO 0919 ROUTE 0420.

TIME:19:44: 0

ROGER!

TK 1 2 REPORTING REACHED DESTINATION 1624

TK 2 3 REPORTING REACHED DESTINATION 2517

TK 32 REPORTING REACHED DESTINATION 1717

TANK 5 3 REPORTING FROM LOCATION 7 23 RIVER OBSTACLE AHEAD
with MAIN CHARACTEREstics AS FOLLOWS:=

DIRECTION NORTH WEST 400 SOUTH EAST

APPROX WIDTH 100 METERS

APPROX DEPTH 75 CMS

SHOULD I NEGOTIATE THE OBSTACLE or CHANGE COURSE ?

TYPE IN A "C" FOR CHANGING COURSE OR A "GO" TO CONTINUE:GO

TANK 11 REPORTS GIVING EFFECTIVE FIRE ON LN 1123

TANK 21 REPORTS GIVING EFFECTIVE FIRE ON LN 2717

YOUR COMMAND:TK 11 FIRE 6 AP SHELL AT TK 51.

TIME:19:45: 0

TK 3 3 REPORTING REACHED DESTINATION 1517

YOUR COMMAND:TK 23 FIRE 6 HE SHELL LN 2725.

TIME:19:46: 0

TK 1 3 REPORTING REACHED DESTINATION 1922

TK 2 2 REPORTING REACHED DESTINATION 2717

YOUR COMMAND:CONT.

TIME:19:47: 0

TANK 5 3 REPORTING > FROM LOCATION 620 TANK BOGGED DOWN IN MARSHY GR
TANK 23 REPORTS GIVING EFFECTIVE FIRE ON LN 2725
YOUR COMMAND:TK 23 REPORT VISIBILITY TK 41.

TIME:19:48: 0

TANKLOCATION 27 20
CANNOT SEE THAT DISTANCE AT NIGHT
IS NOT VISIBLE TO ME
YOUR COMMAND:TK 23 FIRE 4 AP SHELL LN 2722.

TIME:19:49: 0

YOUR COMMAND:TK 22 FIRE 4 HE SHELL AT TK 41.

TIME:19:50: 0

YOUR COMMAND:CONT.

TIME:19:51: 0

TK 4 1 REPORTING REACHED DESTINATION 2713

TK 5 2 REPORTING REACHED DESTINATION 1728
YOUR COMMAND:TK 41 FIRE 5 HE SHELL LN 2617.

TIME:19:52: 0

YOUR COMMAND:CONT.

TIME:19:53: 0

TANK 41 REPORTS GIVING EFFECTIVE FIRE ON LN 2617
YOUR COMMAND:TK 23 FIRE 6 HE SHELL AT TK 41.

TIME:19:54: 0

YOUR COMMAND:CONT.

TIME:19:55: 0

TANK 41 REPORTING! UNDER ENEMY HE FIRE FROM LOC 2517
TANK 23 REPORTS NUETRALISING ENEMY TK-> LOC 2713
YOUR COMMAND: FREEZE.

TIME: 19:56: 0

YOUR COMMAND: TK 13 MOVE TO 1925.

TIME: 19:56: 0

ROGER!

YOUR COMMAND: TK 12 MOVE TO 1927.

TIME: 19:56: 0

ROGER!

YOUR COMMAND: TK 23 MOVE TO 2727.

TIME: 19:56: 0

ROGER!

YOUR COMMAND: TK 22 MOVE TO 3133 ROUTE 2532.

TIME: 19:56: 0

ROGER!

YOUR COMMAND: TK 32 FIRE 10 HE SHELL LN 0923.

TIME: 19:56: 0

YOUR COMMAND: TK 11 MOVE TO 1923.

TIME: 19:56: 0

ROGER!

YOUR COMMAND: CONT.

TIME: 19:56: 0

TANK 1 2 REPORTING FROM LOCATION 16 24 RIVER OBSTACLE AHEAD
with MAIN CHARACTEREstics AS FOLLOWS: =

	DIRECTION	NORTH	=>>	SOUTH
APPROX WIDTH	25	METERS		
APPROX DEPTH	25	CMS		
SHOULD I NEGOTIATE THE OBSTACLE or CHANGE COURSE ?				
TYPE IN A "C" FOR CHANGING COURSR OR A "GO" TO CONTINUE: GO				

TANK 1 1 REPORTING FROM LOCATION 15 19 RIVER OBSTACLE AHEAD
with MAIN CHARACTEREstics AS FOLLOWS:-

DIRECTION NORTH WEST =>> SOUTH EAST
APPROX WIDTH 100 METERS
APPROX DEPTH 75 CMS
SHOULD I NEGOTIATE THE OBSTACLE or CHANGE COURSE ?
TYPE IN "C" FOR CHANGING COURSE OR A "GO" TO CONTINUE:C
TANK ALREADY ON MOVE. DO YOU WANT TO CHANGE STATUS ?Y
FOR CHANGING ONLY DESTINATION TYPE "D"
FOR CHANGING ONLY ROUTE TYPE "R"
FOR COMPLETE CHANGING "C"
FOR RETURN WITHOUT CHANGING "W"
TYPE OF CHANGE REQUIRED ?D
NEW DESTINATION:1525
YOUR COMMAND:0001.

TIME:19:57: 0

TK 1 2 REPORTING REACHED DESTINATION 1927

TANK 1 1 REPORTING FROM LOCATION 15 20 RIVER OBSTACLE AHEAD
with MAIN CHARACTEREstics AS FOLLOWS:-

DIRECTION WEST =>> SOUTH EAST
APPROX WIDTH 100 METERS

APPROX DEPTH 75 CMS

SHOULD I NEGOTIATE THE OBSTACLE OR CHANGE COURSE ?
TYPE IN A "C" FOR CHANGING COURSE OR A "GO" TO CONTINUE:GO
TANK 32 REPORTS GIVING EFFECTIVE FIRE ON LN 923
YOUR COMMAND:TK 13 FIRE 4 AP SHELL AT TK 32.

TIME:19:58: 0

TK 1 3 REPORTING REACHED DESTINATION 1925

TANK 32 REPORTS GIVING EFFECTIVE FIRE ON LN 0923
YOUR COMMAND:TK 52 FIRE 4 HE SHELL LN 1725.

TIME:19:59: 0

TK 1 1 REPORTING REACHED DESTINATION 1525

TANK 52 REPORTING!UNDER ENEMY AP FIRE FROM LOC 1924
YOUR COMMAND:TK 21 MOVE 2 KM NORTH.

TIME:20: 0: 0

ROGER!

TANK 52 REPORTS GIVING EFFECTIVE FIRE ON LN 1725
YOUR COMMAND:TK 23 FIRE 8 HE SHELL LN 3133.

TIME:20: 1: 0

TK 2 3 REPORTING REACHED DESTINATION 2727

YOUR COMMAND:TK 12 FIRE 4 AP SHELL LN 1728.

TIME:20: 2: 0

TANK 43 REPORTING!UNDER ENEMY HE FIRE FROM LOC 2625
TANK 23 REPORTS NUETRALISING ENEMY TK-> LOC 3032
TANK 23 REPORTS GIVING EFFECTIVE FIRE ON LN 3133
YOUR COMMAND:CONT.

TIME:20: 3: 0

TK 2 1 REPORTING REACHED DESTINATION 2515

TANK 43 REPORTING!UNDER ENEMY HE FIRE FROM LOC 2625
TANK 23 REPORTS GIVING EFFECTIVE FIRE ON LN 3133

TANK 52 REPORTING!UNDER ENEMY AP FIRE FROM LOC 1927
TANK 12 REPORTS GIVING EFFECTIVE FIRE ON LN 1728
YOUR COMMAND:TK 22 REPORT LOCATION.

TIME:20: 4: 0

TANK 2 OF TROOP 2 REPORTING

LOCATION	X	Y
	25	31

YOUR COMMAND:TK 23 MOVE TO 3133.

TIME:20: 5: 0

ROGER!

TANK 2 3 REPORTING > FROM LOCATION 2828
TANK HAS RUN INTO ENEMY MINEFIELD!!
YOUR COMMAND:TK 13 FIRE 4 SMOKE SHELL LN 2129.

TIME:20: 6: 0

YOUR COMMAND:TK 12 MOVE TO 2130.

TIME:20: 7: 0

ROGER!

TK 2 2 REPORTING REACHED DESTINATION 3133

TANK 13 REPORTS GIVING EFFECTIVE FIRE ON LN 2129
YOUR COMMAND:TK 13 MOVE TO 2128.

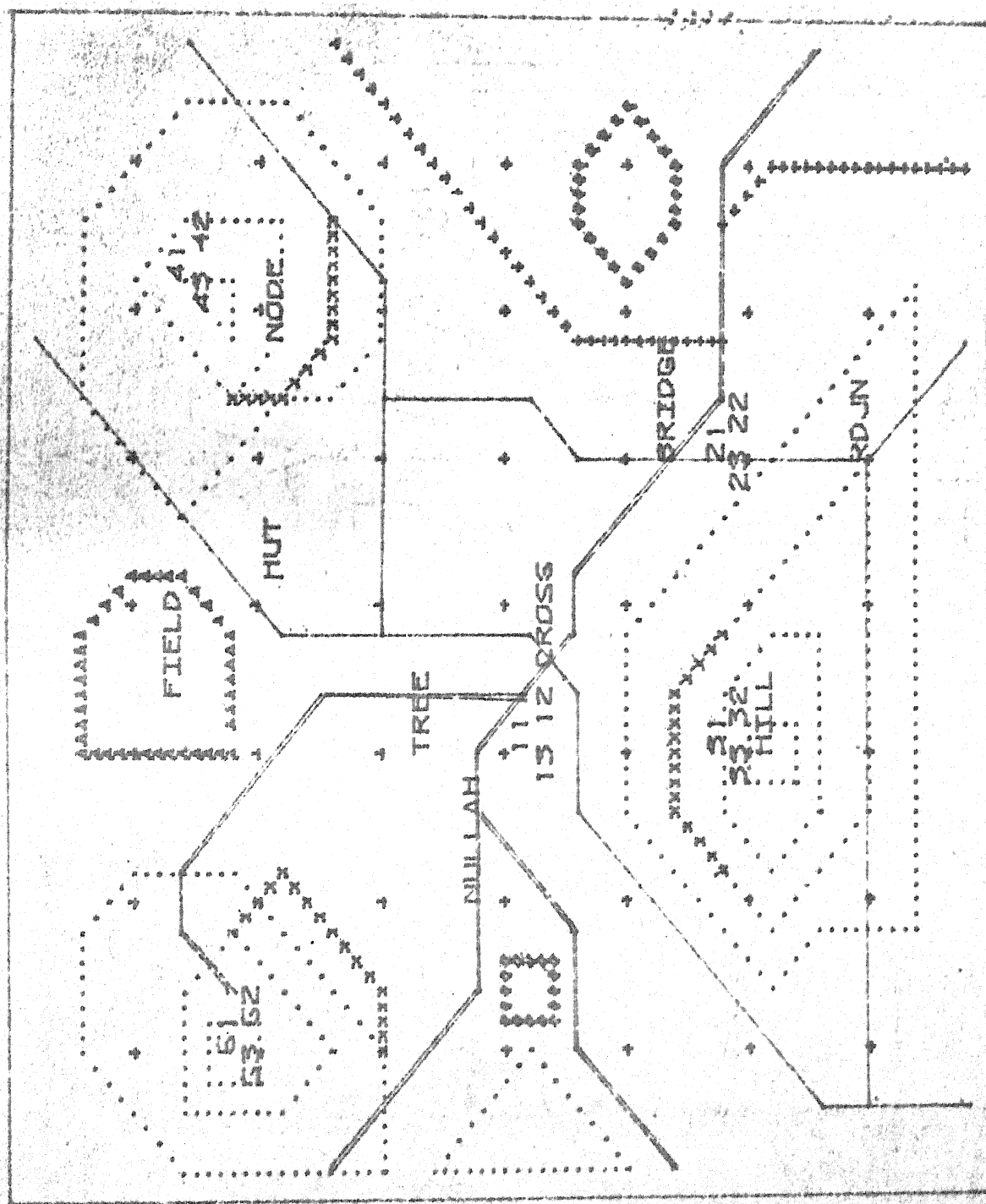
TIME:20: 8: 0

ROGER!

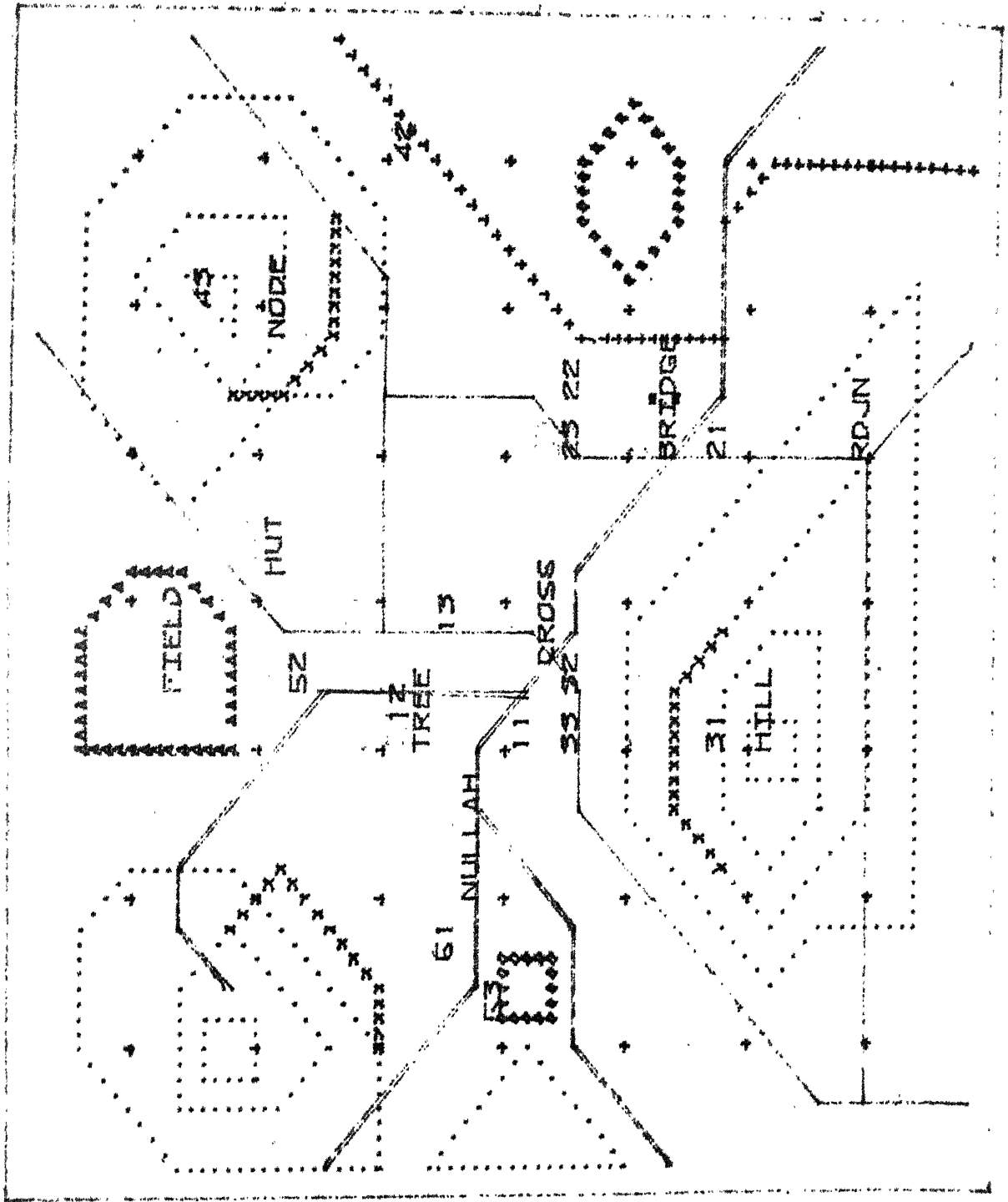
TK 1 3 REPORTING REACHED DESTINATION 2128
YOUR COMMAND:CONT.

TIME:20: 9: 0

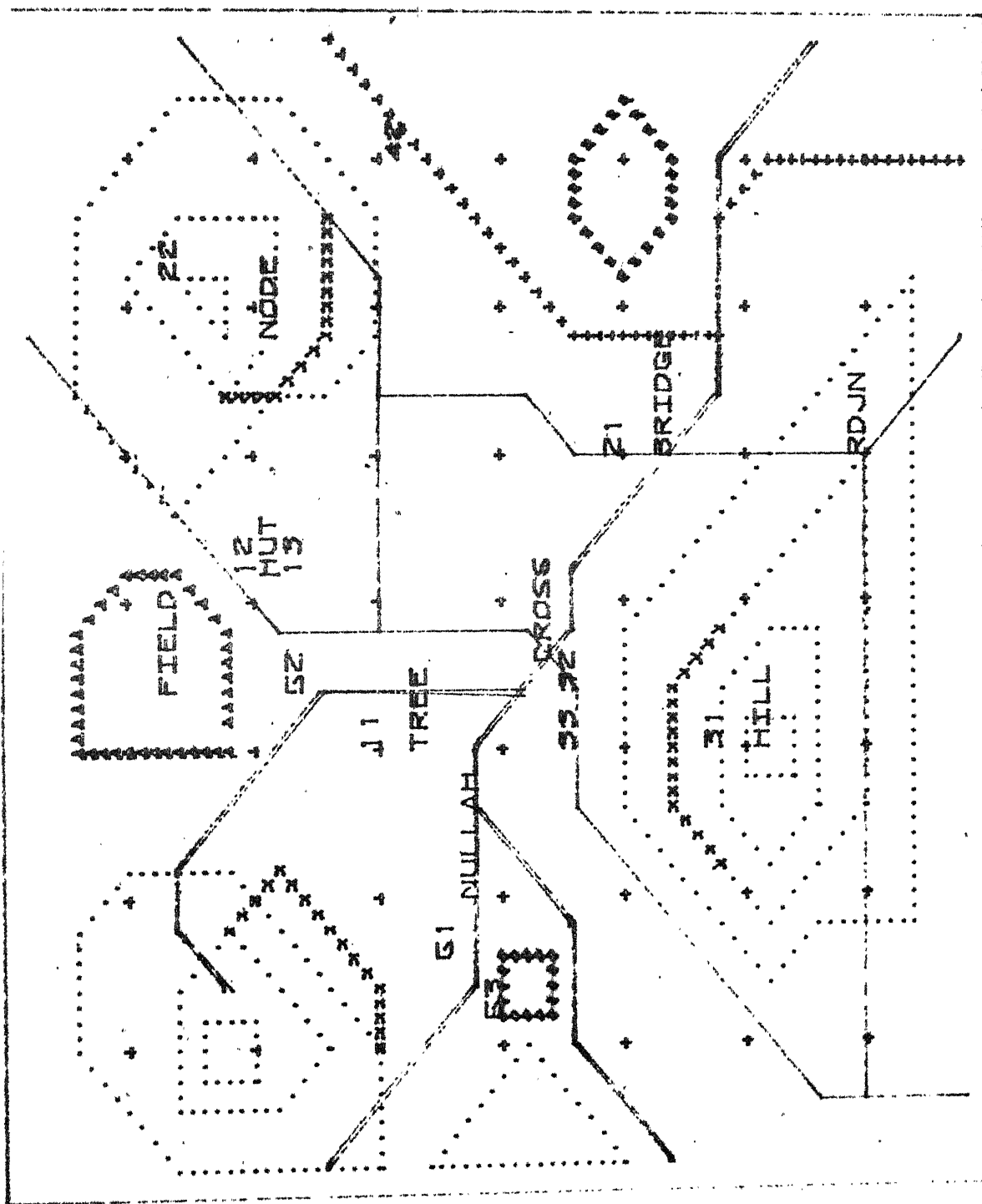
TK 1 2 REPORTING REACHED DESTINATION 2130
YOUR COMMAND:END.



MAP - 1



MAP-2



MAP - 3

APPENDIX C


```

005700 DEPRESSION:=integer(*MAXIMUM DEPRESSION POSSIBLE +/-1*)
005800 end;
005900 LMPTR:=packed array[1..210 of char;
006000 NAMEXDRD:=packed array[1..1410 of char;
006100 GRAVSS=0.;R;GROWTHCHAR;
006200 LMPTR:=A;GROWTHCHAR;
006300 LMPTR:=A;GROWTHCHAR;
006400 VALXDRD:=packed array[1..1410 of char;
006500 VALXDRD:=packed array[1..1410 of char;
006600 VALXDRD:=packed array[1..1410 of char;
006700 VALXDRD:=packed array[1..1410 of char;
006800 VALXDRD:=packed array[1..1410 of char;
006900 VALXDRD:=packed array[1..1410 of char;
007000 VALXDRD:=packed array[1..1410 of char;
007100 VALXDRD:=packed array[1..1410 of char;
007200 VALXDRD:=packed array[1..1410 of char;
007300 VALXDRD:=packed array[1..1410 of char;
007400 VALXDRD:=packed array[1..1410 of char;
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008600 VALXDRD:=packed array[1..1410 of char;
008700 VALXDRD:=packed array[1..1410 of char;
008800 VALXDRD:=packed array[1..1410 of char;
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009600 VALXDRD:=packed array[1..1410 of char;
009700 VALXDRD:=packed array[1..1410 of char;
009800 VALXDRD:=packed array[1..1410 of char;
009900 VALXDRD:=packed array[1..1410 of char;
010000 VALXDRD:=packed array[1..1410 of char;
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010200 VALXDRD:=packed array[1..1410 of char;
010300 VALXDRD:=packed array[1..1410 of char;
010400 VALXDRD:=packed array[1..1410 of char;
010500 VALXDRD:=packed array[1..1410 of char;
010600 VALXDRD:=packed array[1..1410 of char;
010700 VALXDRD:=packed array[1..1410 of char;
010800 VALXDRD:=packed array[1..1410 of char;
010900 VALXDRD:=packed array[1..1410 of char;
011000 VALXDRD:=packed array[1..1410 of char;
011100 VALXDRD:=packed array[1..1410 of char;
011200 VALXDRD:=packed array[1..1410 of char;

```

[illegible]

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COMMAND GIVE CARRY REPORT);
IF YOU WANT THESE COMMANDS TO BE
TYPED THEN TYPE CARRY TO START NOW);
END;

end;

procedure

begin

end;

procedure MSG(primarily used to print out messages originating from the programme);
begin
end;

case of

1: WRITELN(TTY, "THIS TANK ALREADY ON MOVE");

2: WRITELN(TTY, "EXPLOSIVES A D/R/C/W HENCE "N" ASSUMED");

3: WRITELN(TTY, "TANK CANNOT MOVE");

4: WRITELN(TTY, "TANK CANNOT MOVE");

5: WRITELN(TTY, "TANK CANNOT MOVE");

6: WRITELN(TTY, "TANK CANNOT MOVE");

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42: WRITELN(TTY, "TANK CANNOT MOVE");

43: WRITELN(TTY, "TANK CANNOT MOVE");

44: WRITELN(TTY, "TANK CANNOT MOVE");

45: WRITELN(TTY, "TANK CANNOT MOVE");

[illegible]

[illegible]

```

0370 J:=integer;
0371 for J:=1 to 12 do WORD[J]:='';
0372 J:=1; while ((LINEINPUT[J]='#') or (LINEINPUT[J]='')) do I:=I+1;
0373 ERRORPOINT:=I;
0374 if I<40 then
0375 begin
0376 repeat
0377 if I<13 then WORD[I]:=LINEINPUT[I];
0378 J:=J+1; I:=I+1;
0379 until
0380 ((LINEINPUT[I]='#') or (LINEINPUT[I]='')) or (LINEINPUT[I]='')) or
0381 ((LINEINPUT[I]='') or (LINEINPUT[I]=''));
0382 if J>12 then
0383 goto 3503;
0384 end
0385 else ERROR(7)
0386 end;
0387
0388 procedure READINPUT; (*READS DIRECTLY INPUT UP TO 12 CHARACTERS*)
0389 (* reads directive from tty and stores them in WORD.
0390 * to interactive communication *)
0391
0392 var
0393 YCH:char; I:integer;
0394 begin
0395 for I:=1 to 12 do WORD[I]:='';
0396 YCH:=
0397 while ICH#'' do READ(TTY, INCH);
0398 while ((not EOL(TTY)) and (I<13) and (INCH#')) do
0399 begin
0400 WORD[I]:=INCH; I:=I+1; READ(TTY, INCH);
0401 end;
0402 if I>12 then goto 3503;
0403 else
0404 if EOL(TTY) then WORD[I]:=INCH
0405 end;
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03930  ISNUMBER:=false?
03940  If TESTNUMBER then
03950  begin
03960  PROC(6);WRITE(TTY,"WULD YOU LIKE TO SUBSTITUTE 145 NUMBER 22");
03970  BREAK:READC8;
03980  If C8="Y" then
03990  begin
04000  WRITE(TTY,"GIVE NEW NUMBER:");BREAK:READNCRD;014822
04010  end;
04020  end
04030  C8?
04040  TESTNUMBER:=false
04050  end;
04060  procedure skipp:lines pp,(*SKIPS 'p' LINES WHILE OUTPUTTING*)
04070  (*used to skip lines on tty for clarity of presentation*)
04080  (***)
04090  var J:integer;
04100  begin
04110  for J:=1 to p do WRITELN(TTY)
04120  end;
04130  (***)
04140  function YES:NO:bool:(*CHECKS ANS*)
04150  (***)
04160  begin
04170  READC8;
04180  If C8="Y" then YES:=true
04190  else YES:=false
04200  end;
04210  (***)
04220  function REUSE(X:integer):real:(*reduces the scale from integer to real*)
04230  (***)
04240  begin
04250  REUSE:=X/40
04260  end;
04270  (***)
04280  procedure CONVERT(I:integer;var A,B:integer):
04290  (*32bit is the smallest value and five the largest and easiest of
04300  the 32bit is the smallest value and five the largest and easiest of
04310  the 32bit is the smallest value and five the largest and easiest of
04320  the 32bit is the smallest value and five the largest and easiest of
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04460  the 32bit is the smallest value and five the largest and easiest of
04470  the 32bit is the smallest value and five the largest and easiest of
04480  the 32bit is the smallest value and five the largest and easiest of

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00500 else error(11)
00501 and
00502 if (word="FIRST" ) then error(12)
00503
00504 add; if you want the table of landmarks ?);
00505 break;
00506 read;
00507 if (word="Y" then
00508 read;
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06730 UNTIL (CHR='V')OR(CUE='V'))
06740 WRITECH(TRY,POV)GIVING THE LOCATION OF VARIOUS FIGURES OF YOUR SQUARES);
06750 WRITECH(TRY,POV)GIVING REQUIRED TO GIVE ONLY FOUR FIGURE GRID REFERENCES);
06760 FOR J:=1 TO 5 DO
06770 BEGIN
06780   WRITE(TRY,POV,POV,J:3,'');BREAK;
06790   READ(POV;HUTANK;CONVERT(INVAL,X,Y));
06800   ADD:=1;
06810   FOR I:=1 TO 3 DO
06820     WITH LOC(VAL,I,I) DO
06830       CONVERT:=E;CONV:=TYPOFTANK;
06840       FUELCAP:=TANKCHAR(TYPOTANK);FUELES + TANKCHAR(TYPOTANK);
06850       FUELCAP:=E;
06860       LOCINE:=I;
06870       IF I=1 THEN
06880         MAPCORD.X:=X;MAPCORD.Y:=Y;
06890       ELSE
06900         MAPCORD.X:=X+ADD;MAPCORD.Y:=Y-1;ADD:=ADD*(-1);
06910     END;
06920   END;
06930   AMNCAP.TYP1:=AMN1;
06940   AMNCAP.TYP2:=AMN2;AMNCAP.TYP3:=AMN3;ALT:=SPIDCHAR(X,Y).ALTITUDE;
06950   WITH STATUS DO
06960     BEGIN
06970       BTGSED:=false;MOVING:=false;
06980       FIRING:=false;CUPCLACLOSED:=true;
06990       CUPCLACLOSED:=false;CANMOV:=true;
07000       CANSHOT:=true;SHOCKED:=false
07010     END
07020     AND
07030     AND
07040     AND
07050     AND
07060     AND;
07070     *****
07080     procedure CONVERTGRID(var GRX,GRY:letter;X,Y:integer);
07090     (* converts the integer coordinates
07100     (* and outputs GRX,GRY as chars
07110     (* these outputs are used for storage and in printing out messages *)
07120     *****
07130     var
07140       I,J,V1,V1:integer;
07150     begin
07160       X1:=X;Y1:=Y;
07170       for I:=2 downto 1 do
07180         begin
07190           J:=(X1)MOD(10);X1:=(X1)DIV(10);GRX(I1):=CHR(J+ORD('0'));
07200           J:=(Y1)MOD(10);Y1:=(Y1)DIV(10);GRY(I1):=CHR(J+ORD('0'));
07210         end
07220       end;
07230     *****
07240     procedure UPDATETIME:(*UPDATES THE TIME ELAPSED IN THE SIM,SEC*)
07250     *****
07260     begin
07270       if not FREEZE
07280

```

```

07290 then
07300 begin
07310 TIMESSEC:=TIMESSEC+TIMESTEP;
07320 if TIMESSEC>=60 then
07330 begin
07340 TIMESMIN:=TIMESMIN+TIMESSECdiv(60);TIMESSEC:=(TIMESSEC)mod(60)
07350 end;
07360 if TIMESMIN>=60 then
07370 begin
07380 TIMEHR:=TIMEHR+(TIMESMIN)div(60);
07390 TIMESMIN:=TIMESMIN mod 60;
07400 end;
07410 if TIMEHR>=24 then TIMEHR:=TIMEHR-24;
07420
07430 write('PRV, TIME:',TIME,TIMEHR:2,',',TIMEMIN:2,',',TIMESSEC:2)
07440
07450 procedure NUMDIR(DIRECTION(DIR:RANGE;var DIRWORD:LETTERWORD);
07460 /* converts DIRECTION to the cardinal direction.
07470 used for outputting -like flow of river */
07480 var I,J:integer;
07490 begin
07500 case DIR of
07510 D:DIRWORD:='NORTH';
07520 E:DIRWORD:='EAST';
07530 S:DIRWORD:='SOUTH';
07540 W:DIRWORD:='WEST';
07550 others:
07560 begin
07570 I,J:=1 to 5 do
07580 for I:=1 to 3 do
07590 for J:=1 to 3 do
07600 with I*J*100+J*10+I, J:STATUS do
07610 if SHOCKED then SHOCKED:=false
07620
07630 I,J:=integer;
07640 begin
07650 for I:=1 to 5 do
07660 for J:=1 to 3 do
07670 with I*J*100+J*10+I, J:STATUS do
07680 if SHOCKED then SHOCKED:=false
07690
07700 end;
07710 procedure GETDIRECTION(X1,X2,Y1,Y2:integer;var DIRECTION:integer);
07720
07730 var
07740 XOISP,YOISP:integer;ANGLE:real;
07750
07760
07770 procedure CALLANGLE(X(BASE:integer);
07780
07790 begin
07800 if ANGLE>=2.35 then DIRECTION:=0
07810 else
07820 if ANGLE>=0.42 then DIRECTION:=ABS(1-BASE)
07830 else DIRECTION:=ABS(2-BASE)
07840 end;

```

```
07850 *****\
07860 procedure CALLANGUEY( BASE:integer); *****\
07870 *****\
07880 begin
07890   if ANGLE <= 0.42 then DIRECTION:=ABS(BASE-2)
07900   else
07910     if ANGLE <= 2.35 then DIRECTION:=ABS(BASE-3)
07920     else DIRECTION:=4
07930   end;
07940   begin
07950     XDISP:=X2-X1;
07960     YDISP:=Y2-Y1;
07970     if XDISP<0 then
07980       if YDISP>0 then DIRECTION:=0
07990       else DIRECTION:=4
08000     else
08010       if XDISP>0 then DIRECTION:=4
08020       else
08030         begin
08040           ANGDIS:=ABS(YDISP/XDISP);
08050           if ANGDIS>0 then
08060             if ANGDIS>0 then CALLANGUEY(0)
08070             else CALLANGUEY(0)
08080           else
08090             if YDISP>0 then CALLANGUEY(8)
08100             else CALLANGUEY(8)
08110           end;
08120         end;
08130       ***\
08140       ***\
08150       ***\
08160       ***\
08170       ***\
08180       ***\
08190       ***\
08200       SPLITARRAY:=packed array[1..2]of 0..99;
08210       var
08220         VIEW HEIGHT,DEPTH,I,DEGREE:integer;
08230         CUR1,CUR2:integer;
08240         FIXED,XORO:packed array[1..10]of char;
08250         DIRECTIONS:array[0..MAXPOINTS]:boolean;
08260         FIRSTPOINTI,FIRSTPOINTJ,CURRENTPOINTI,CURRENTPOINTJ:SPLITARRAY;
08270       ***\
08280       ***\
08290       ***\
08300       ***\
08310       ***\
08320       ***\
08330       ***\
08340       ***\
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09980       ***\
09990       ***\

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08410 GRIDCHAR(p1,p2).GROUND:=PTR;
08420 GRIDCHAR(p1,p2).TYPE:=DIRECTION;
08430 end;
08440 procedure GROUND(p1,p2:integer);
08450 (*procedure for ground, it has 2 or more characteristics at the same time *)
08460 begin
08470   GROUND:=1..9;
08480   begin
08490     GROUND:=GRIDCHAR(p1,p2).TYPE;
08500     GRIDCHAR(p1,p2).TYPE:=GROUND;
08510     GROUND:=NEXTPTR;
08520     GROUND:=GRIDCHAR(p1,p2).GROUND;
08530     GRIDCHAR(p1,p2).GROUND:=PTR;
08540     GROUND:=NEXTPTR;
08550     GROUND:=NEXTPTR;
08560     GROUND:=NEXTPTR;
08570     GROUND:=NEXTPTR;
08580     GROUND:=NEXTPTR;
08590     GROUND:=NEXTPTR;
08600     GROUND:=NEXTPTR;
08610     GROUND:=NEXTPTR;
08620     GROUND:=NEXTPTR;
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08640     GROUND:=NEXTPTR;
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08670     GROUND:=NEXTPTR;
08680     GROUND:=NEXTPTR;
08690     GROUND:=NEXTPTR;
08700     GROUND:=NEXTPTR;
08710     GROUND:=NEXTPTR;
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09140     GROUND:=NEXTPTR;
09150     GROUND:=NEXTPTR;
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09180     GROUND:=NEXTPTR;
09190     GROUND:=NEXTPTR;
09200     GROUND:=NEXTPTR;
09210     GROUND:=NEXTPTR;
09220     GROUND:=NEXTPTR;
09230     GROUND:=NEXTPTR;
09240     GROUND:=NEXTPTR;
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09270     GROUND:=NEXTPTR;
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09360     GROUND:=NEXTPTR;
09370     GROUND:=NEXTPTR;
09380     GROUND:=NEXTPTR;
09390     GROUND:=NEXTPTR;
09400     GROUND:=NEXTPTR;
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09490     GROUND:=NEXTPTR;
09500     GROUND:=NEXTPTR;
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09580     GROUND:=NEXTPTR;
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09600     GROUND:=NEXTPTR;
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09620     GROUND:=NEXTPTR;
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09640     GROUND:=NEXTPTR;
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09680     GROUND:=NEXTPTR;
09690     GROUND:=NEXTPTR;
09700     GROUND:=NEXTPTR;
09710     GROUND:=NEXTPTR;
09720     GROUND:=NEXTPTR;
09730     GROUND:=NEXTPTR;
09740     GROUND:=NEXTPTR;
09750     GROUND:=NEXTPTR;
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09770     GROUND:=NEXTPTR;
09780     GROUND:=NEXTPTR;
09790     GROUND:=NEXTPTR;
09800     GROUND:=NEXTPTR;
09810     GROUND:=NEXTPTR;
09820     GROUND:=NEXTPTR;
09830     GROUND:=NEXTPTR;
09840     GROUND:=NEXTPTR;
09850     GROUND:=NEXTPTR;
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09880     GROUND:=NEXTPTR;
09890     GROUND:=NEXTPTR;
09900     GROUND:=NEXTPTR;
09910     GROUND:=NEXTPTR;
09920     GROUND:=NEXTPTR;
09930     GROUND:=NEXTPTR;
09940     GROUND:=NEXTPTR;
09950     GROUND:=NEXTPTR;
09960     GROUND:=NEXTPTR;
09970     GROUND:=NEXTPTR;
09980     GROUND:=NEXTPTR;
09990     GROUND:=NEXTPTR;
10000     GROUND:=NEXTPTR;

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089700 end;
089800 end;
089900 procedure READCHAR: (READS A CHARACTER FROM THE FILE MAPDAT);
090000 ***
090100 ***
090200 ***
090300 var
090400   AD:char;
090500   begin READ(MAPDAT,AD);
090600   until CH#';
090700   while not (EQU(MAPDAT)or(ALP#')) do READ(MAPDAT,AD);
090800   end;
090900 ***
091000 ***
091100 ***
091200 ***
091300 ***
091400 ***
091500 ***
091600 ***
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094400 ***
094500 ***
094600 ***
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094800 ***
094900 ***
095000 ***
095100 ***
095200 ***

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```

09530 procedure FILLGRID;
09540 (* completes the grid heights after the contours have been described *)
09550 type
09560   GTRD = record
09570     HT, NO: integer
09580   end;
09590 var
09600   STACK: array 0..1000 of GTRD;
09610   TOP, I, J: integer;
09620   procedure FILLGRID(FROMNO, TONNO, HT: integer);
09630   (*fills the heights HT between pts FROMNO to TONNO *)
09640   var
09650     V: integer;
09660     begin
09670       if TOP=0 then V:=1;
09680       else
09690         begin
09700           for K:=FROMNO to TONNO do
09710             if GTRD[CHARIK,I].ALTITUDE=0 then
09720               GTRD[CHARIK,I].ALTITUDE:=HT;
09730             STACK[TOP].HT:=0; STACK[TOP].NO:=0; TOP:=TOP+1
09740           end;
09750           add;
09760           add;
09770           procedure PUSH(HEIGHT NUMBER: integer);
09780           (*stores the height HEIGHT in stack for matching *)
09790           var
09800             PUSHSTACK: boolean;
09810             PUSHSTACK:=false;
09820             begin
09830               PUSHSTACK:=false;
09840               if TOP<2 then PUSHSTACK:=true
09850               else
09860                 begin
09870                   if ((STACK[TOP].HT>STACK[TOP-1].HT)and(HEIGHT>STACK[TOP].HT))
09880                     then PUSHSTACK:=true
09890                     else
09900                       if ((STACK[TOP].HT<STACK[TOP-1].HT)and(HEIGHT<STACK[TOP].HT))
09910                         then PUSHSTACK:=
09920                           true
09930                           else
09940                             if HEIGHT=STACK[TOP-1].HT then
09950                               begin FILLGRID(STACK[TOP-1].NO, NUMBER, HEIGHT); STACK[TOP].HT:=0;
09960                               STACK[TOP]
09970                               .NO:=0; TOP:=TOP-1;
09980                             end
09990                             else V:=1;
10000               end;
10010             end;
10020             if PUSHSTACK then
10030               begin
10040                 TOP:=TOP+1;
10050                 if TOP>10 then V:=1;
10060                 else
10070                   begin
10080

```

```

10090 with STACK[TOP] to
10100 begin
10110 HT:=HT+SH:0:=0;
10120 end;
10130 end;
10140 end;
10150 end;
10160 procedure INITSTACK;
10170 (* Initialises the stack for starting *)
10180 a;
10190 b;
10200 var
10210 IS:integer;
10220 begin
10230 for IS:=0 to 10 do with STACK[IS] do
10240 begin
10250 HT:=0;00:=0
10260 end;
10270 end;
10280 end;
10290 for I:=1 to 40 do
10300 begin
10310 INITSTACK;
10320 for J:=1 to 40 do
10330 begin
10340 if GRIDCHAR[I,J].ALTITUDE#0 then
10350 begin
10360 if STACK[TOP].HT#GRIDCHAR[I,J].ALTITUDE then
10370 PUSH(GRIDCHAR[I,J].ALTITUDE,I)
10380 else
10390 FILUGRID(STACK[TOP].NO,I,STACK[TOP].AY)
10400 end;
10410 end;
10420 end;
10430 end;
10440 begin
10450 for I:=1 to 7 do
10460 begin
10470 case I of
10480 1:FIXEDWORD:='RIVER'
10490 2:FIXEDWORD:='CANAL'
10500 3:FIXEDWORD:='ROAD'
10510 4:FIXEDWORD:='CRCP/SEIUD'
10520 5:FIXEDWORD:='MINING'
10530 6:FIXEDWORD:='MARSHY'
10540 7:FIXEDWORD:='CLIFF'
10550 end;
10560 LOCALCHAR;ERROR:=false;
10570 REPEAT if CH#V;
10580 exit if I<3 then
10590 begin
10600 READ(MAPAT,LOTH);
10610 READ(MAPDPT,DEPTH);
10620 end
10630 else
10640

```



```

110650 if i=7 then
110651   begin
110652     READ(MAPDAT, HEIGHT)
110653   end;
110654   READNUMBER; FIRSTPOINT:=true;
110655   SPLIT(LASTPOINT);
110656   loop
110657     READNUMBER;
110658     exit if ((CURR)=FINISH
110659             'or(not ISNUMBER)or(ERROR));
110660     SPLIT(CURRPOINT);
110661     GETDIRECTION(LASTPOINT[1], LASTPOINT[2],
110662                 NEXTPOINT[1], NEXTPOINT[2], DIRECTION);
110663     repeat
110664       CURRENTPOINT:=LASTPOINT;
110665       CUR1:=CURRENTPOINT[1]; CUR2:=CURRENTPOINT[2];
110666       CALCNEXTGRID(CUR1, CUR2, DIRECTION);
110667       CURRENTPOINT[1]:=CUR1; CURRENTPOINT[2]:=CUR2;
110668       if ((CURRENTPOINT[1]<41)and(CURRENTPOINT[1]>0)
110669           and(CURRENTPOINT[2]<41)and(CURRENTPOINT[2]>0)) then
110670         begin
110671           if i<7 then
110672             begin
110673               FILLADVGRID; FILLPRESENTGRID;
110674             end
110675           else GRIDCHAR(LASTPOINT[1], LASTPOINT[2], ALPHADE
110676                       :=HEIGHT;
110677             LASTPOINT:=CURRENTPOINT; FIRSTPOINT:=false;
110678           end
110679         else
110680           begin
110681             USE(1);
110682             ERROR:=true;
110683           end
110684         until
110685           ((CURRENTPOINT=NEXTPOINT)or (ERROR));
110686         if CURRENTPOINT=NEXTPOINT then USE(1);
110687       end;
110688     end;
110689     FILLALITUDE;
110690     WRITE(OUTPUT, "IMPORTANT: note that the map details have been taken
110691           from your file
110692           SPLIT(2);
110693   end;
110694   *****
110695   function ISVISIBLE(LDC1X, LDC1Y, LDC2X, LDC2Y: integer; on: char): boolean;
110696   (* checks if the loc1 and loc2 are visible taking into consideration all other fact
110697   except that of line of sight *)
110698   *****
110699   label 10;
110700   var
110701     FINISH, MIGHT: boolean;
110702     DISTANCE, TIME: integer;
110703     *****
110704     function CHECKVISIBILITY(LDC1X, LDC1Y, LDC2X, LDC2Y: integer): boolean;
110705     *****

```



```

11210 (* checks if the line of sight visibility is there or not *)
11220 var
11230   CHECK_X, LOC1: boolean;
11240   STARTX, STARTY, ENDX, ENDY, CURRENTX, CURRENTY: integer;
11250   CURR_ANGLE, ANGLE, C: real;
11260   ***
11270   procedure CALCNEXTX;
11280   ***
11290   begin
11300     CURRENTX:=CURRENTX + INCR;
11310     CURRENTY:=TRUNC(4*CURRENTX+C*0.5)
11320   end;
11330   ***
11340   procedure CALCNEXTY;
11350   ***
11360   begin
11370     CURRENTY:=CURRENTY + INCR;
11380     CURRENTX:=TRUNC((CURRENTY-C)/4)+0.5)
11390   end;
11400   ***
11410   begin
11420     if ABS(LOC1X-LOC2X) > ABS(LOC1Y-LOC2Y) then CHECKX:=true
11430     else CHECKX:=false;
11440     C:=(LOC2Y-LOC1Y)/(LOC2X-LOC1X);
11450     C:=LOC1Y-M*LOC1X;
11460     if GRIDCHAR(LOC1X,LOC1Y).ALTITUDE > GRIDCHAR(LOC2X,LOC2Y).ALTITUDE then
11470       LOC1:=true
11480     else
11490       LOC1:=false;
11500     CALCULATEDIST(LOC1X,LOC1Y,LOC2X,LOC2Y,DISTANCE);
11510     if LOC1 = true then
11520       begin
11530         STARTX:=LOC2X;STARTY:=LOC2Y;
11540         ENDX:=LOC1X;ENDY:=LOC1Y;
11550       end
11560     else
11570       begin
11580         STARTX:=LOC1X;STARTY:=LOC1Y;
11590         ENDX:=LOC2X;ENDY:=LOC2Y;
11600       end;
11610     CURRENTX:=STARTX;CURRENTY:=STARTY;
11620     ANGLE:=GRIDCHAR(STARTX,STARTY).ALTITUDE - GRIDCHAR(ENDX,ENDY).ALTITUDE/
11630     DISTANCE;
11640     if CHECKX then
11650       if ENDX > STARTX then INCR:=1
11660       else INCR:=-1
11670     else
11680       if ENDY > STARTY then INCR:=1
11690       else INCR:=-1;
11700     CURR_ANGLE:=0.0;
11710     while (CURR_ANGLE<ANGLE)and((CURRENTX#ENDX)or(CURRENTY#ENDY))do
11720       begin
11730         if CHECKX then CALCNEXTX
11740         else CALCULATEDIST(CURRENTX,CURRENTY,ENDX,ENDY,DISTANCE);
11750         CALCULATE:=((GRIDCHAR(ENDX,ENDY).
11760

```

```

12330 end
12340 else
12350 begin
12360 ERROR(1);
12370 ERR:=TRUE;
12380 end
12390 end
12400 end
12410 else
12420 begin
12430 READCORD:=MARK;
12440 if ISCH=REP then
12450 begin
12460 LOCX:=TKDAT[1];NUMWORD[1];NUMWORD[2];MAPCORD:X;
12470 LOCY:=TKDAT[1];NUMWORD[1];NUMWORD[2];MAPCORD:Y;
12480 end
12490 else ERR:=true
12500 end
12510 ;
12520 if not ERR then
12530 begin
12540 case CH of
12550 'F':WRITELOC(FF,'TANK',LOCATION,LOC2X,LOC2Y);
12560 others:
12570 end;
12580 if ISVISIBLE(LOC1X,LOC1Y,LOC2X,LOC2Y,CH) then WRITELOC(FF,'IS VISIBLE TOO (F)');
12590 else WRITELOC(FF,'IS NOT VISIBLE (F,ME)');
12600 end;
12610
12620
12630
12640 procedure REPORT(CH:char);
12650 (* output details like FUEL BALANCE, LOCATION, LOCATION OR FUEL BALANCE;
12660 details from the record for the tank IK,JK *)
12670
12680 begin
12690 WRITELOC(FF,'TANK ',JK:2,' OF TROOP ',IK:2,' REPORTING:12);WRITELOC(FF);
12700 if CH='F' then
12710 begin WRITELOC(FF,'FUEL BALANCE:':25);WRITELOC(FF,TKDAT[IK,JK].FUELCAP:5,' LOC
12720 )
12730 end;
12740 if CH='L' then
12750 begin WRITELOC(FF,'LOCATION:':10);WRITELOC(FF,'X:':10,'Y:':10);
12760 CONVERTGRIDref(GRX,GRY,TKDAT[IK,JK].MAPCORD,X,TKDAT[IK,JK].MAPCORD,Y);
12770 WRITELOC(FF,GRX:21,GRY:10)
12780 end;
12790 if CH='E' then
12800 begin WRITELOC(FF,'ENEMY ACTIVITY:');WRITELOC(FF,'ENEMY SEEN AT LOC 628105');
12810 end
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```

```

12900 begin
12901   READWORD;
12902   if word = '' then
12903     AP:=false; H:=false; S:=false;
12904   repeat
12905     if word = 'AP' then
12906       begin AP:=true; READWORD
12907       end;
12908     if word = 'H' then
12909       begin H:=true; READWORD
12910       end;
12911     if word = 'S' then
12912       begin S:=true; READWORD
12913       end;
12914     if word = 'ALL' then
12915       begin ALL:=true; READWORD
12916       end;
12917   until (word = 'AP'
12918   and ALL=true;
12919   WRITELN(TTY, 'TANK', JK, JK:6, 'OF GROUP', JK:6, 'REPORTING AMMUNITION BALANCE', JK:6);
12920   if ((AP=true) or (ALL=true)) then WRITELN(TTY, 'AP', JK:6, 'TANK DATA', JK:6, 'AMMUNITION BALANCE', JK:6);
12921   then
12922     WRITELN(TTY, 'SWAKE', JK:6, 'TANK DATA', JK:6, 'AMMUNITION BALANCE', JK:6);
12923   if (H=true) or (ALL=true) then WRITELN(TTY, 'H', JK:6, 'TANK DATA', JK:6, 'AMMUNITION BALANCE', JK:6);
12924   *****
12925   procedure TANKSTATUS (TA:boolean); (**REPORTS STATUS OF OWN TANK OR OTHER TANK**)
12926   (* depending on the type of command reports the STATUS of self or of other tanks
12927   like ROGUE, MOVING, etc *)
12928   *****
12929   var
12930     J, K, I: integer; TEMP: packed array[1..4] of char; LOCREC: boolean;
12931   begin LOCREC:=false;
12932     if JA=true then
12933       if word = 'LOC' then
12934         READWORD; for K:=1 to 4 do TEMP[K]:=word[K];
12935         LOCREC:=true
12936       end
12937     else
12938       begin
12939         J:=NUMWORD[2]; I:=NUMWORD[1]; READWORD;
12940         if word = 'LOC' then
12941           LOCREC:=true; for K:=1 to 6 do TEMP[K]:=word[K];
12942         end
12943       end
12944     end;
12945     WRITELN(TTY, 'TANK', JK:6, 'OF GROUP', JK:6, 'STATUS', JK:6);
12946     if JA=true then

```

```

13450 begin TK:=1; TK:=3;
13460 RTT:=LOC(TTY, REPORTING STATUS OF TANK:30, T:3, OF TANK:10, T:30);
13470 if LOCATED=TRUE then RTT:=LOC(TTY, located at grid ref , T:30);
13480 end
13490 else
13500 RTT:=LOC(TTY, REPORTING STATUS OF SELF:30);
13510 if LOCATED=TRUE then RTT:=LOC(TTY, with STATUS 30
13520 RTT:=LOC(TTY, RTT) to with STATUS 30
13530 skip(2);
13540 if RTT=LOC(TTY, RTT) then MSG(4);
13550 if RTT=LOC(TTY, RTT) then MSG(5);
13560 else RTT:=LOC(TTY, RTT) then MSG(6);
13570 if RTT=LOC(TTY, RTT) then MSG(7);
13580 if not CANVOW then
13590 begin MSG(8);
13600 if RTT=LOC(TTY, RTT) then MSG(9);
13610 if RTT=LOC(TTY, RTT) then MSG(10);
13620 end;
13630 end;
13640 skip(2);
13650 end;
13660 skip(2);
13670 end;
13680 skip(2);
13690 skip(2);
13700 skip(2);
13710 skip(2);
13720 skip(2);
13730 skip(2);
13740 skip(2);
13750 skip(2);
13760 skip(2);
13770 skip(2);
13780 skip(2);
13790 skip(2);
13800 skip(2);
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13920 skip(2);
13930 skip(2);
13940 skip(2);
13950 skip(2);
13960 skip(2);
13970 skip(2);
13980 skip(2);
13990 skip(2);
14000 skip(2);

```



```

14570 begin
14580   UP:=UPPUPC-20000;
14590   while (UP<100000000)and (UP#011) do
14600     begin
14610       if (UP#0>UPC-4000) then UP:=UP*.RUINK
14620       else UP:=UP*.RUIK
14630       if (UPC-4000=1000) then
14640         begin
14650           ISLANDMARK:=UPPUPC-UP*.GR
14660         end;
14670       end;
14680       *****
14690       procedure CHECKPOINTS (var A,B:integer);
14700       (* checks two points, firstly if the word is a number or LANDMARK, if it is
14710         then converts and tells its difference in A, B *)
14720       var C:integer;
14730       C:=integer;
14740       if (C#0) then
14750         if (C#0) then CHECKLANDMARK(C);
14760         if (C#0) then ISLANDMARK(C);
14770         if (C#0) then CONVERT(C,A,B)
14780         else end
14790       end;
14800       *****
14810       procedure ENTERS (* ENTERS THE ROUTE TO BE TAKEN BY THE FAIR ON THE MOVE *)
14820       (* this is part of the MOVE table filling. It fills the route to be taken
14830       (* for the task specified in input command. *)
14840       (* max current points limited to 10, the time of processing and
14850       (* the current points are limited to 10, the time of processing and
14860       (* stored in CURR OBJECTIVE *)
14870       is stored in CURR OBJECTIVE *)
14880       var J,I,C:integer; A,B:integer;
14890       begin
14900         I:=0; for J:=1 to 10 do
14910           begin
14920             MO*.ROUTE[J].X:=0;
14930             MO*.ROUTE[J].Y:=0;
14940           end;
14950         readword;
14960         exit if (word#'); or (I=11));
14970         CHECKPOINTS(A,B);
14980         if (ISNUMBER or ISLANDMARK) then
14990           begin
15000             I:=I+1; MO*.ROUTE[I].X:=A; MO*.ROUTE[I].Y:=B
15010           end
15020         else ERROR(18)
15030         end;
15040       end;
15050
15060
15070
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```

```

15130  IF NOT ISLANDMARK THEN FIGURESTMDVtab;
15140  END;
15150  *****
15160  *****
15170  *****
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15680  *****
15690  *****

```

```

15690 end
15700 else ERROR(17)
15710 end;
15720 and;
15730 procedure PROCEDURE100; (**ANALYSES THE OBJECTIVE PART OF THE LOWE COORDINATES**)
15740 (** THIS PROCEDURE CHECKS THE OBJECTIVE PART OF THE LOWE COORDINATES **)
15750 forward move to objective is there **)
15760 forward move to objective is there **)
15770 var
15780 C: integer; (**integer**)
15790 begin
15800 READ (C,CHECK:FILE(A,B));
15810 if IS (C,CHECK) or IS (C,CHECK) then
15820 begin
15830 C:=C+1; (**integer**)
15840 if C=0 then
15850 if C=0 then
15860 if C=0 then
15870 if C=0 then
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16230 if C=0 then
16240 if C=0 then

```



```

16250 READINPUT;
16260 CHECKCOORDS(0,0);
16270 IF ISVIA(0) OF 16 THEN MARK then
16280 GO TO 16280;
16290 IF X:=16 THEN STATE:=true;
16300 IF Y:=16 THEN STATE:=true;
16310 GO TO 16310;
16320 ELSE
16330 BEGIN
16340 READCOORDS(1,1);
16350 GO TO 16350;
16360 END
16370
16380 *****
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16400 *****
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16800 *****

```

```

16810 begin
16820 CHECKMOVTAB:=REMOVED;
16830 if ISINTERMEDIATE then
16840 begin
16850 if MOVNO=0 then
16860 begin
16870 if AR^.STATE=1 then
16880 if AR^.STATE=1 then
16890 begin
16900 else
16910 end
16920 else
16930 begin
16940 if MOVNO=0 then
16950 if MOVNO=0 then
16960 else
16970 end
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19990 end
20000 end

```

```

BEGIN
WRITE(OUT,"THIS TANK ALREADY FIRING,BALLANCE OF,FIELD,DOWN.",ENDL);
WRITE(OUT,"GET IT BACK.");
WRITE(OUT,"GO TO CHANGE TARGET ?");
IF YES THEN GO TO SUBROUTINE 3(TEMP)
ELSE GOTO 1;
END.
END.

```

[illegible][illegible][illegible]

```

PROBABILITY:=0.98;VALUE:=1.0;
if BOGGED then
  begin VALUE:=0.8;PROBABILITY:=0.3;
  end;
if ADVIUS then
  begin VALUE:=0.98;PROBABILITY:=0.98;
  end;

```

```

end;
if FURLING then PROBABILITY:=0.97*VALUE;
if CUPOLACLOSE then PROBABILITY:=0.9*VALUE;
end;
end;

```

[illegible]

```

      DESTTK(I,J)#, then
      IF C-HITPRD3==PROBABILITY(CIK,JK)*PRDBABLIITY(FP*.DESTTK(I),FP*.DESTTK(2))
      ELSE FP=C-HITPRD3==PROBABILITY(CIK,JK);
      ELSE TIME=TIME+INCKDAFIK,JKI.CODTME;
      **
      **
      ** end.

```

[illegible]

[illegible]

```

19990 FP^.Y(PJFA^):=3
19991 end
19992 else
19993   begin ERROR(23);
19994   goto 15
19995 end;
19996 READ WORD;
19997 if ((WORD='SHEUG' ')) then
19998   begin
19999     READ WORD;
20000     if WORD='V'
20001     then
20002       begin
20003         READ WORD;
20004         if ((WORD='TANK' ')) then
20005           begin
20006             JOIN:=true;
20007             MSG(17);
20008             FP^.DESTLOC.X:=TNKDAT[FP^.DESTTK[1],FP^.
20009             DESTTK[2]];
20010             MAPCORD.X:=
20011             FP^.DESTLOC.Y:=TNKDAT[FP^.DESTTK[1],FP^.
20012             DESTTK[2]];
20013             MAPCORD.Y:=
20014             JOIN:=true;
20015             end;
20016             end
20017           else
20018             begin
20019               ERROR(24);
20020               goto 15
20021             end
20022           else ERROR(25)
20023           end
20024         else
20025           if WORD='LV'
20026           then GETLOCATION
20027           else ERROR(27)
20028           end
20029         else MSG(18)
20030         end
20031         if JOIN=true then JOINFIRETab;
20032       15:
20033       end;
20034       *****\
20035       procedure PROCESSMOVtank(PTR:MPIR);
20036       (* processes the move of the tank , checking for the obstacles and taking action

```

```

119050  ***
119060  const GROUNDFACTOR=0.95;
119070  var
119080  PIPECTION:RANGE:=PFACT*PIR, XPRV, YPRV:integer;FINISH:boolean;
119090  SPECU:DIS:RANGE:=PFACT*PIR, XPRV, YPRV:integer;FINISH:boolean;
119100  procedure CHANGEDIRECTION;
119110  (* Gets the next point of collective move the bird of has been reached *)
119120  (***)
119130  begin
119140  if PIR<OBJECTIVE < PIR.CORRECTIVE then
119150  if PIR.CORRECTIVE < PIR.CORRECTIVE then
119160  begin
119170  XPRV:=PIR.CORRECTIVE;
119180  YPRV:=PIR.CORRECTIVE;
119190  end
119200  else
119210  begin
119220  XPRV:=PIR.CORRECTIVE;
119230  YPRV:=PIR.CORRECTIVE;
119240  end
119250  end;
119260  (***)
119270  procedure COMPUTE;
119280  (** Computes the time for the tank has taken to move from one pt to another *)
119290  (***)
119300  var
119310  X1,Y1,X2,Y2:integer;FACOR:real;LPRK:1..5;
119320  PIR:GRI:integer;DISTANCE:integer;
119330  (***)
119340  procedure CHECKCROSSOBSTACLE(GROUND:RANGE);
119350  (** Checks for the obstacle crossing for ground type GROUND *)
119360  (***)
119370  begin
119380  LPRK:=5;
119390  if PIR.CORRECTIVE < PIR.CORRECTIVE then
119400  if PIR.CORRECTIVE < PIR.CORRECTIVE then
119410  begin
119420  with PIR do
119430  begin
119440  PIR:=true;CAMOV:=false;CAMSHOOT:=false
119450  end
119460  end
119470  else
119480  begin
119490  if ((GROUND=2) and (TANKCHARITYPOFFPARK).SPECULAR < PIR.CORRECTIVE) then
119500  begin
119510  MSG(12);MSG(15);FINISH:=true;
119520  PIR.STATE:=false
119530  end
119540  else
119550  begin
119560  if CROSSED:=true;
119570  end;
119580  (***)
119590  procedure REPORTWATEROBSTACLE(GROUND:RANGE);
119600  (** Reports the encountering of obstacle and asks for the action to be taken *)
119610  (***)

```

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[illegible]

```

0170 REACH=0;S1=0;S2=0;S3=0;S4=0;S5=0;S6=0;S7=0;S8=0;S9=0;S10=0;S11=0;S12=0;S13=0;S14=0;S15=0;S16=0;S17=0;S18=0;S19=0;S20=0;S21=0;S22=0;S23=0;S24=0;S25=0;S26=0;S27=0;S28=0;S29=0;S30=0;S31=0;S32=0;S33=0;S34=0;S35=0;S36=0;S37=0;S38=0;S39=0;S40=0;S41=0;S42=0;S43=0;S44=0;S45=0;S46=0;S47=0;S48=0;S49=0;S50=0;S51=0;S52=0;S53=0;S54=0;S55=0;S56=0;S57=0;S58=0;S59=0;S60=0;S61=0;S62=0;S63=0;S64=0;S65=0;S66=0;S67=0;S68=0;S69=0;S70=0;S71=0;S72=0;S73=0;S74=0;S75=0;S76=0;S77=0;S78=0;S79=0;S80=0;S81=0;S82=0;S83=0;S84=0;S85=0;S86=0;S87=0;S88=0;S89=0;S90=0;S91=0;S92=0;S93=0;S94=0;S95=0;S96=0;S97=0;S98=0;S99=0;S100=0;S101=0;S102=0;S103=0;S104=0;S105=0;S106=0;S107=0;S108=0;S109=0;S110=0;S111=0;S112=0;S113=0;S114=0;S115=0;S116=0;S117=0;S118=0;S119=0;S120=0;S121=0;S122=0;S123=0;S124=0;S125=0;S126=0;S127=0;S128=0;S129=0;S130=0;S131=0;S132=0;S133=0;S134=0;S135=0;S136=0;S137=0;S138=0;S139=0;S140=0;S141=0;S142=0;S143=0;S144=0;S145=0;S146=0;S147=0;S148=0;S149=0;S150=0;S151=0;S152=0;S153=0;S154=0;S155=0;S156=0;S157=0;S158=0;S159=0;S160=0;S161=0;S162=0;S163=0;S164=0;S165=0;S166=0;S167=0;S168=0;S169=0;S170=0;S171=0;S172=0;S173=0;S174=0;S175=0;S176=0;S177=0;S178=0;S179=0;S180=0;S181=0;S182=0;S183=0;S184=0;S185=0;S186=0;S187=0;S188=0;S189=0;S190=0;S191=0;S192=0;S193=0;S194=0;S195=0;S196=0;S197=0;S198=0;S199=0;S200=0;S201=0;S202=0;S203=0;S204=0;S205=0;S206=0;S207=0;S208=0;S209=0;S210=0;S211=0;S212=0;S213=0;S214=0;S215=0;S216=0;S217=0;S218=0;S219=0;S220=0;S221=0;S222=0;S223=0;S224=0;S225=0;S226=0;S227=0;S228=0;S229=0;S230=0;S231=0;S232=0;S233=0;S234=0;S235=0;S236=0;S237=0;S238=0;S239=0;S240=0;S241=0;S242=0;S243=0;S244=0;S245=0;S246=0;S247=0;S248=0;S249=0;S250=0;S251=0;S252=0;S253=0;S254=0;S255=0;S256=0;S257=0;S258=0;S259=0;S260=0;S261=0;S262=0;S263=0;S264=0;S265=0;S266=0;S267=0;S268=0;S269=0;S270=0;S271=0;S272=0;S273=0;S274=0;S275=0;S276=0;S277=0;S278=0;S279=0;S280=0;S281=0;S282=0;S283=0;S284=0;S285=0;S286=0;S287=0;S288=0;S289=0;S290=0;S291=0;S292=0;S293=0;S294=0;S295=0;S296=0;S297=0;S298=0;S299=0;S300=0;S301=0;S302=0;S303=0;S304=0;S305=0;S306=0;S307=0;S308=0;S309=0;S310=0;S311=0;S312=0;S313=0;S314=0;S315=0;S316=0;S317=0;S318=0;S319=0;S320=0;S321=0;S322=0;S323=0;S324=0;S325=0;S326=0;S327=0;S328=0;S329=0;S330=0;S331=0;S332=0;S333=0;S334=0;S335=0;S336=0;S337=0;S338=0;S339=0;S340=0;S341=0;S342=0;S343=0;S344=0;S345=0;S346=0;S347=0;S348=0;S349=0;S350=0;S351=0;S352=0;S353=0;S354=0;S355=0;S356=0;S357=0;S358=0;S359=0;S360=0;S361=0;S362=0;S363=0;S364=0;S365=0;S366=0;S367=0;S368=0;S369=0;S370=0;S371=0;S372=0;S373=0;S374=0;S375=0;S376=0;S377=0;S378=0;S379=0;S380=0;S381=0;S382=0;S383=0;S384=0;S385=0;S386=0;S387=0;S388=0;S389=0;S390=0;S391=0;S392=0;S393=0;S394=0;S395=0;S396=0;S397=0;S398=0;S399=0;S400=0;S401=0;S402=0;S403=0;S404=0;S405=0;S406=0;S407=0;S408=0;S409=0;S410=0;S411=0;S412=0;S413=0;S414=0;S415=0;S416=0;S417=0;S418=0;S419=0;S420=0;S421=0;S422=0;S423=0;S424=0;S425=0;S426=0;S427=0;S428=0;S429=0;S430=0;S431=0;S432=0;S433=0;S434=0;S435=0;S436=0;S437=0;S438=0;S439=0;S440=0;S441=0;S442=0;S443=0;S444=0;S445=0;S446=0;S447=0;S448=0;S449=0;S450=0;S451=0;S452=0;S453=0;S454=0;S455=0;S456=0;S457=0;S458=0;S459=0;S460=0;S461=0;S462=0;S463=0;S464=0;S465=0;S466=0;S467=0;S468=0;S469=0;S470=0;S471=0;S472=0;S473=0;S474=0;S475=0;S476=0;S477=0;S478=0;S479=0;S480=0;S481=0;S482=0;S483=0;S484=0;S485=0;S486=0;S487=0;S488=0;S489=0;S490=0;S491=0;S492=0;S493=0;S494=0;S495=0;S496=0;S497=0;S498=0;S499=0;S500=0;S501=0;S502=0;S503=0;S504=0;S505=0;S506=0;S507=0;S508=0;S509=0;S510=0;S511=0;S512=0;S513=0;S514=0;S515=0;S516=0;S517=0;S518=0;S519=0;S520=0;S521=0;S522=0;S523=0;S524=0;S525=0;S526=0;S527=0;S528=0;S529=0;S530=0;S531=0;S532=0;S533=0;S534=0;S535=0;S536=0;S537=0;S538=0;S539=0;S540=0;S541=0;S542=0;S543=0;S544=0;S545=0;S546=0;S547=0;S548=0;S549=0;S550=0;S551=0;S552=0;S553=0;S554=0;S555=0;S556=0;S557=0;S558=0;S559=0;S560=0;S561=0;S562=0;S563=0;S564=0;S565=0;S566=0;S567=0;S568=0;S569=0;S570=0;S571=0;S572=0;S573=0;S574=0;S575=0;S576=0;S577=0;S578=0;S579=0;S580=0;S581=0;S582=0;S583=0;S584=0;S585=0;S586=0;S587=0;S588=0;S589=0;S590=0;S591=0;S592=0;S593=0;S594=0;S595=0;S596=0;S597=0;S598=0;S599=0
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[illegible]

21290 GROUNDFACTOR(CRIOCHARLY2,Y21,TYPEGROUND);

21300 GRADIENT(FACOR;

21310 end;

21320 if ((not FINISH) or (CROSSED)) then

21330 begin

21340 PIR^.LOC.X:=X2;PIR^.LOC.Y:=Y2;

21350 SPEED:=TRUNC((SPEED*FACTOR));

21360 INKDATA(I,KJ,KI,NABCORD,X:=X2;INKDATA(I,KJ,NABCORD,Y:=Y2;

21370 CURRENTTIME:=TRUNC((36*(DISTANCE)/(SPEED*10)));

21380 UPDATEREAD:INKDATA(I,KJ,KI,DRIFTAS:=CURRECT);

21390 end

21400 end;

21410 begin

21420 TIMECOUNT:=0;FINISH:=false;FINISH:=true;

21430 CHANGEDIRECTION;

21440 SKIP(3);CROSSED:=false;

21450 IK:=(PIR^.JANAYD)DIV(10);JK:=(PIR^.JANX0)DIV(10);

21460 CURRENTTIME:=0;

21470 repeat

21480 GETDIRECTION(PIR^.LOC.X,NEXIX,PIR^.LOC.Y,NEXTI,DIRECTION);

21490 COMPUTETIME;

21500 TIMECOUNT:=TIMECOUNT+CURRENTTIME;

21510 if ((PIR^.LOC.X=PIR^.DEST.X) and (PIR^.LOC.Y=PIR^.DEST.Y)) then

21520 begin

21530 FINISH:=true;REACHEDestination:=true;INKDATA(I,KJ,NABCORD,Y:=Y2;FINISH:=false

21540 end;

21550 if not FINISH then

21560 if ((NEXIX=PIR^.LOC.X) and (NEXTI=PIR^.LOC.Y)) then

21570 begin

21580 PIR^.CORROBJECTIVE:=PIR^.CORROBJECTIVE+1;

21590 CHANGEDIRECTION

21600 end

21610 until ((TIMESTEP<(TIMECOUNT+.5*(CURRENTTIME)) or (FINISH)) or (REACHEDestination));

21620 *****

21630 procedure MOVEBACKS;

21640 (**moves the tasks from a location to another when command has been given *)

21650 *****

21660 var

21670 TEMP,PIR:MPIR;

21680 begin

21690 PIR:=MOVETARROOT.ULINK;

21700 while PIR#nil do

21710 begin

21720 REACHEDestination:=false;

21730 if PIR^.STATE then PROCESSMOVEBACK(PIR);

21740 TEMP:=PIR;ULINK;

21750 if REACHEDestination then DELETEMOVETAR(TEMP)

21760 end

21770 end;

21780 procedure FIRE;

21790 (**FIRE the shell that has been commanded for the task to fire *)

21800 *****

21810 var

[illegible]

[illegible]

```

22970 begin
22980 case 015TYPE of
22990 0:
23000   if ANTYPE=2 then
23010     begin
23020       case ANSTYPE of
23030       1: with PKDAT(I,J).STATUS do
23040         begin
23050           CAMSHOOT:=false;
23060           SHOCKED:=true;
23070         end;
23080       2: PKDAT(I,J).STATUS.CAMMOV:=
23090         false;
23100       3: REPAIRHT(I,J)
23110         end
23120       end
23130     else PKDAT(I,J).STATUS.SHOCKED:=true;
23140   1:
23150     if ANTYPE=2 then
23160       begin
23170         case ANSTYPE of
23180         1: with PKDAT(I,J).STATUS do
23190           begin
23200             CAMSHOOT:=false;
23210             SHOCKED:=true;
23220           end;
23230         2: PKDAT(I,J).STATUS.CAMMOV:=
23240           false;
23250         3: REPAIRHT(I,J)
23260           end
23270         end
23280       else
23290         if ANSTYPE=2 then PKDAT(I,J).STATUS.
23300           CAMOV:=false
23310         else
23320           begin
23330             PKDAT(I,J).STATUS.SHOCKED:=true;
23340             PKDAT(I,J).STATUS.CAMSHOOT:=false
23350           end;
23360         2:
23370           if ANTYPE=3 then PKDAT(I,J).STATUS.
23380             CAMMOV:=false
23390           else
23400             PKDAT(I,J).STATUS.SHOCKED:=true;
23410           others:
23420             end;
23430           end;
23440         end;
23450       end;
23460       begin
23470         for II:=1 to 5 do
23480           for JJ:=1 to 5 do
23490             begin
23500               if (PKDAT(II,JJ).MAPCOR.X=HT(X) and
23510                 (PKDAT(II,JJ).MAPCOR.Y=HT(Y)) then
23520

```

[illegible]


```

end;
if Lp = 0 then GRAPHMAP := 0;
end;
procedure DRAWMAP;
begin
  (* draws the tracks at the location they are at *)
  var I, J: integer;
  begin
    TRACE[3] := '*';
    TRACE[4] := '*';
    for J := 1 to 5 do
      begin
        TRACE[J] := CHR(ORD('*') + J);
        for I := 1 to 3 do
          begin
            TRACE[I] := CHR(ORD('*') + I);
            TRACE[REDUCE(PKDATA[I], J, MAPORD(I, J), MAPORD(I, J), 0)];
            STRING(CNAME);
          end;
        end;
      end;
    end;
  end;
  (* draws the location of all of the shells *)
  var X, Y: integer;
  begin
    while EOF(FIRE) do
      begin
        READ(COORD(X, Y));
        LINE(COORD(X, Y));
        MARKER(X);
      end;
    end;
  end;
  (* draws the map on the graphic display *)
  var XX, YY: real;
  begin
    SP := 0;
    H := 0;
    INCX := 1;
    LASTX := 0;
    LASTY := 0;
    READ(REDUCE(X, Y));
    MARKER(X);
  end;
  (* reads interactive communication *)
  var INCH: char;
  begin
    for I := 1 to 12 do
      begin
        INCH := INCH + 1;
        while (NOT EOF(4ABDAT)) and (INCH = 0) do
          continue;
        end;
      end;
    end;
  end;
end;

```



```

begin
  FOR J:=1 TO 40 DO READ(MAP(J), P(J));
end;
if I > 12 then ASO(3)
else
  if EOLN(MAP(40)) then XOLN:=1;
  while not EOLN(MAP(40)) do READ(MAP(40), P(40));
end;
***
procedure DRAW;
  (* draws the details of the map as follows:
  ***
  var
    LASTX, LASTY: integer;
  ***
  procedure FILLSETUP(X, LASTX, Y, LASTY: integer);
    (* used for get loopset's points for the display purpose *)
    ***
    var
      PX, PY: real;
      TEMP: integer;
    begin
      TEMP:=LASTX-X; PX:=X; PY:=Y;
      if TEMP=1 then PX:=X+0.5
      else
        if TEMP=(-1) then PX:=LASTX+0.5;
        TEMP:=LASTY-Y;
        if TEMP=1 then PY:=Y+0.5
        else
          if TEMP=(-1) then PY:=LASTY+0.5;
          if ((X#LASTX) or (Y#LASTY)) then
            begin
              LINE(PX/40, PY/40, 0); MARKER(X, Y);
            end;
          end;
        begin
          loop
            READLN;
          until not ISNUMBER;
          CONVERT(J,IVAL,X1,Y1);
          LASTX:=X; LASTY:=Y;
        repeat
          READLN(MAP,X,Y);
          FILLSETUP(X, LASTX, Y, LASTY);
          LINE(REQUEST(X), REQUEST(Y), 0);
          MARKER(X, Y);
          LASTX:=X; LASTY:=Y;
        until ((X=X1) and (Y=Y1));
        end;
      ***
    procedure READCHAR: (* reads a character from the FILE MAP(40) *)
      ***
      var
        up: char;
      begin

```

```

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```

```

25770 repeat READ(MAPDAT,CH)
25780 until CH#(EOL-(MAPDAT)OR(ALP=.)) to READ(MAPDAT,CH);
25790 while not (EOL-(MAPDAT)OR(ALP=.)) to START MAP->);MARKX;READLN(LP);
25800 end;
25810 begin
25820 RESET(MAPDAT);RESET(MAP);
25830 WRITE(LNCTY,CIVE,RETURN TO START MAP->);MARKX;READLN(LP);
25840 GIVE(0,0,0,0);
25850 GIVE(1,0,0,0);
25860 GIVE(0,1,0,0);
25870 GIVE(0,0,1,0);
25880 GIVE(0,0,0,1);
25890 YY:=0;
25900 CSIZE:=60;
25910 for I:=1 to 7 do
25920 begin
25930 XX:=0;
25940 YY:=YY+0.125;
25950 for J:=1 to 7 do
25960 begin
25970 XX:=XX+0.125;
25980 LINE(XX,YY,0);
25990 MARKER(3);
26000 end;
26010 end;
26020 for I:=1 to 7 do
26030 begin
26040 READLN(MAPDAT,);READLN(MAPDAT,);
26050 loop
26060 READLN(MAPDAT,);
26070 exit if CH#';'
26080 if I<3 then
26090 begin
26100 READLN(MAPDAT,);READLN(MAPDAT,);
26110 end
26120 else
26130 if I=7 then READLN(MAPDAT,);
26140 READLN(MAPDAT,SP);
26150 CONVERT(X,Y);
26160 LINE(REDUCE(X),REDUCE(Y),0);
26170 FIRST:=true;
26180 if ((I=1)OR(I=3)) then
26190 begin
26200 loop
26210 READLN(MAPDAT,);
26220 exit if not (ISNUMBER(CONVERT(INVAL,XI,XI))
26230 LINE(REDUCE(XI),REDUCE(YI),0);XINCR:=0.01 OR:=0.0;
26240 if I=1 then
26250 begin
26260 if X=XI then XINCR:=-0.005
26270 else YINCR:=0.005;
26280 if FIRST then
26290 begin FIRST:=false;LASTX:=REDUCE(X)+XINCR;LASTY:=
26300 REDUCE(Y)+YINCR;
26310 end;
26320 LINE(LASTX,LASTY,0);

```

```

LASTIX:=REDUCE(XI)+VINCR;LASTY:=REDUCE(YI)+VINCR;
LINE(CASTA,CASTY,1);
LINE(REDUCE(XI),REDUCE(YI),0);
end;
X:=XI;Y:=YI;
end;
else
begin
case 1 of
1:3:MARK:=3;
2:MARK:=1;
4:MARK:=4;
5:MARK:=5;
6:MARK:=6;
other:MARK:=10;
end;
MARKER(MARK);
DRAW;
end;
end;
end;
end;
DRAWMARK(WORD);DRAWANK;
DRAWAREPT;
WRITECN(TTY,'GIVE <REFUR> TO CLEAR <COMTIME>');DRAWK
CURDEV(1);
end;
*****
procedure COMMANDS;
begin READWORD;
if WORD='REPORT' then REPORT;
else
if WORD='MOVE' then MOVPROCEDURE;
else
if (WORD='FIRE' or (WORD='SHOOT')) then
begin
WRITECN(TTY,'YOUR STATEMENT',20,WORD,15,'NOT RECOGNISED');
BREAK;
end;
end;
*****
procedure TANKNAME;
(* the no of the tank is stored in IK-tankno, JK-tankno.*)
(* if it then checks if the tank is neutralised.*)
(* if it is NEUTRALISED then it is not allowed to be accessed *)
*****
begin
READWORD;
NUMBER;
TANKNUMBER;
IK:=NUMBER(1);JK:=NUMBER(2);
if ((IK<6)and(IK>0)and(JK>0)and(JK<4)) then
begin
if ((not TANKAT(IK,JK).STATUS.NEUTRALISED)and(not TANKA

```

```

26970 when COMMAND=;
26980 end;
26990 else WRITELN(ITY, 'TANK NO ', IK:1, JK:1, ' WRONG GIVE AGAIN');
27000 end;
27010 *****
27020 *****
27030 *****
27040 *****
27050 *****
27060 *****
27070 *****
27080 *****
27090 *****
27100 *****
27110 *****
27120 *****
27130 *****
27140 *****
27150 *****
27160 *****
27170 *****
27180 *****
27190 *****
27200 *****
27210 *****
27220 *****
27230 *****
27240 *****
27250 *****
27260 *****
27270 *****
27280 *****
27290 *****
27300 *****
27310 *****
27320 *****
27330 *****
27340 *****
27350 *****
27360 *****
27370 *****
27380 *****
27390 *****
27400 *****
27410 *****
27420 *****
27430 *****
27440 *****

end;
procedure CHECK;
(* analyses the type of CHECK required and takes action accordingly *)
begin WRITELN(ITY, 'THE FOLLOWING CHECKS ARE POSSIBLE:');
WRITELN(ITY, '15. EXISTING LANDMARKS ARE TYPE "L";');
WRITELN(ITY, '15. EXISTING CURRENTLY MOVING TANKS="T";');
WRITELN(ITY, '15. DRAWING TO THE MAP "M";');
WRITELN(ITY, '15. SETTING TO DRAW THE MAP="S";');
WRITELN(ITY, '15. DELETING THE SET MAP DRAWING="D";');
WRITELN(ITY, '15. RETURN="R";');
BREAK;
case CH of
'L': PRIMTAB(LMRODT); T:=PRINTMOVTAB;
'M': DRAWMAP; S:=MAPREQUIRED:=true; D:=MAPREQUIRED:=false;
others:
begin WRITELN(ITY, 'OUR ', CH, ' NOT RECOGNISED PLEASE RETYPE');
CHECK
end;
end;
begin
INITIALISE;
INITGRID;
INITTANK;
FILTERMAP;
FILTERMAP;
READTIMESTEP;
loop
SKIP(); FREEZE then
if begin ADVETANKS; REMOVESHOCK; FIRE;
end;
if MAPREQUIRED then DRAWMAP;
WRITE(ITY, 'YOUR COMMAND: '); BREAK;
UPDATE TIME;
READLINE; READWORD; TESTNUMBER:=false;
exit if WORD='END'
if WORD='IK'
then
TANKNAME
else
if (WORD='HELPCOMMND' or (WORD='HELP
then HELPCOMMND
else
if WORD='LANDMARK'
then ENTERLM
else
if WORD='CHECK'
then CHECK
else
if WORD='FREEZE'
then FREEZE:=true
else
if (WORD='CONTINUE' or (WORD='CONT
then FREEZE:=
else ERROR(1)

```